Simulations of molecular systems

Large molecules vs. small molecules (rigid or almost rigid)

Vibrating (classical) bonds – pros:

- simplicity and consistency of the model
- code simplicity
- more realistic description of flexibility

Cons:

- technical problems with too stiff springs (short timestep in v MD, short trial moves in MC)
- vibrational frequencies (esp. for hydrogens) are so high that cannot be treated by classical mechanics anyway
- transfer of energy between the fast vibrations and slow degrees of freedom is slow (they are decoupled), unless a stochastic thermostat is used
- flexible models are more complicated theoretically

MC: molecules

Example of a wrong algorithm for a linear molecule with axis (θ, ϕ) :

$$\theta^{\text{tr}} = \theta + \Delta \theta u_{[-1,1]}$$

 $\phi^{\text{tr}} = \phi + \Delta \phi u_{[-1,1]}$

Example of a correct algorithm for a general body:

- choose an axis randomly:
 - any of \hat{x} , \hat{y} , \hat{z} in the body frame
 - any of \hat{x} , \hat{y} , \hat{z} in 3D space
 - any random vector
- igcup rotate by angle $\Delta \alpha u_{[-1,1]}$

where $u_{-1,1}$ is a random number uniformly distributed in interval [-1,1]

Integration of the equations of motion for systems with fixed bond lengths or angles is not the same as the infinitely-large force constant limit of the corresponding flexible system

What to fix:

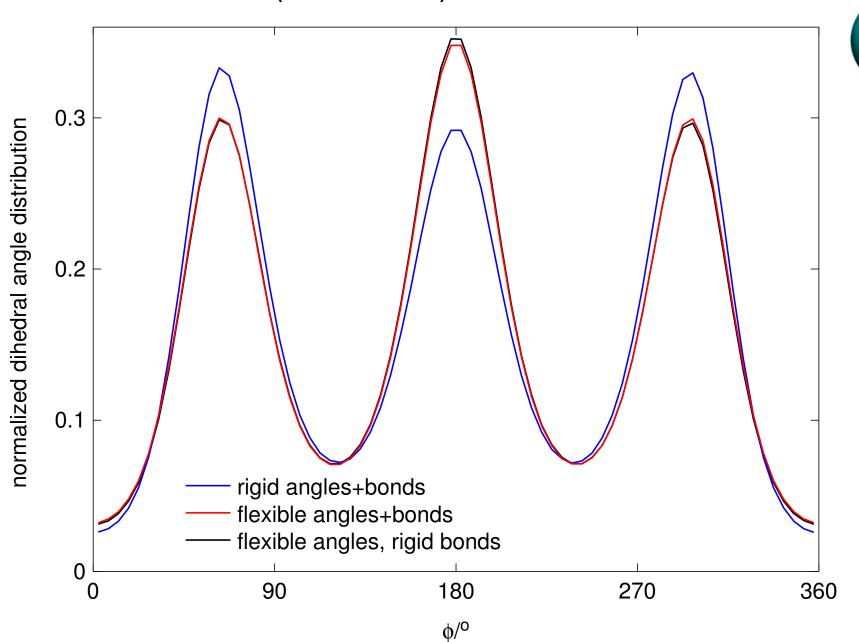
- bonds with hydrogen only longer timestep allowed, slightly worse equipartition
- all bond lengths slightly larger systematic error, not good for rigid geometries (fullerene)
- all bond lengths + angles with hydrogens cheap and less precise, but longer timestep allowed + good equipartition
- all bond lengths + all angles WRONG except small molecules

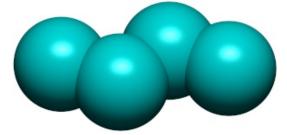
Methods:

- SHAKE (+Verlet)
- Lagrangian constraint dynamics

Dihedral angle distribution of butane

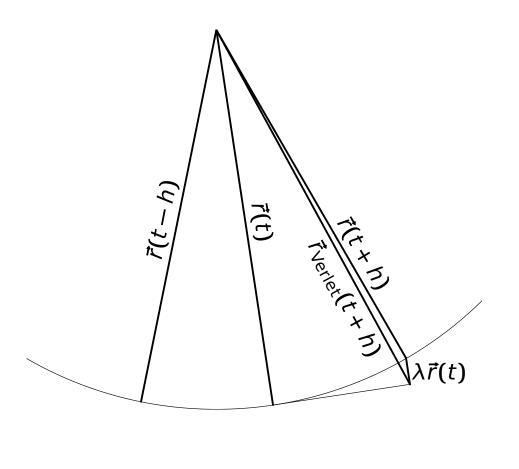






Fixed constraints in MD: SHAKE

Matematical pendulum:



$$\vec{r}(t+h) = \vec{r}_{\text{Verlet}}(t+h) - \frac{h^2}{m} \vec{f}_c(t)$$

$$= 2\vec{r}(t) - \vec{r}(t-h)$$

$$+ h^2 \frac{\vec{f}(t) - \vec{f}_c(t)}{m}$$

$$\frac{h^2 \vec{f}_c(t)}{m} = \lambda \vec{r}(t)$$

$$|\vec{r}(t+h)|^2 = |\vec{r}(t)|^2 = l^2$$

$$[\vec{r}_{\text{Verlet}}(t+h) - \lambda \vec{r}(t)]^2 = \vec{r}(t)^2$$

$$\vec{r}_{\text{Verlet}}(t+h)^2 - 2\lambda \vec{r}_{\text{Verlet}}(t+h) \cdot \vec{r}(t) + \lambda^2 \vec{r}(t)^2 = \vec{r}(t)^2$$

$$\lambda \approx \frac{|\vec{r}_{\text{Verlet}}(t+h)|^2 - |\vec{r}(t)|^2}{2\vec{r}_{\text{Verlet}}(t+h) \cdot \vec{r}(t)}$$

General atom-atom bond:

$$\vec{r}_i(t+h) = \vec{r}_{\text{Verlet},i}(t+h) + \lambda \frac{1/m_i}{1/m_i + 1/m_j} \vec{r}_{ij}$$

$$\vec{r}_j(t+h) = \vec{r}_{\text{Verlet},j}(t+h) - \lambda \frac{1/m_j}{1/m_i + 1/m_j} \vec{r}_{ij}$$

where

$$\lambda = \frac{|\vec{r}_{\text{Verlet},ij}(t+h)|^2 - |\vec{r}_{ij}(t)|^2}{2\vec{r}_{\text{Verlet},ij}(t+h) \cdot \vec{r}_{ij}(t)}$$

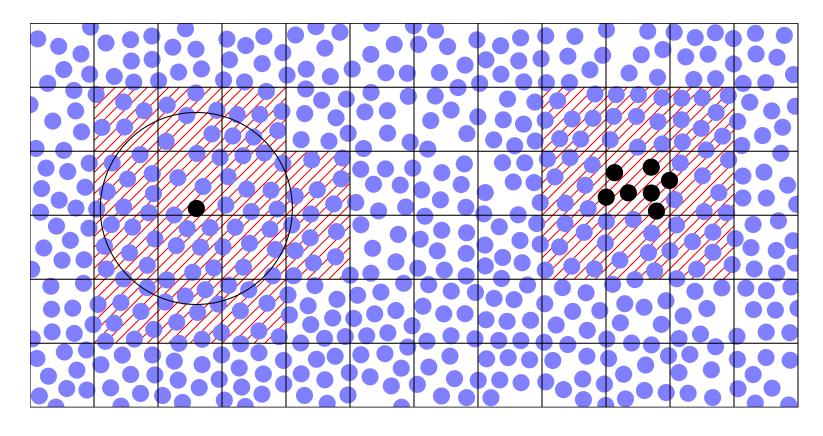
Center-of-mass is conserved (integral of motion)!

Complex molecules: repeat iteratively until converged

Superrelaxation

For short-ranged pair potentials (also r-space Ewald):

- all pairs (N < 300)</p>
- \bigcirc neighbor list ($N \approx 1000$)
- linked-cell list method (N > 1000)



Optimization II

A couple of tricks:

- MD: multiple timestep MD
- MC: multimoves (near the critical point critical slowing-down)
- MC: identity change, non-Boltzmann sampling, . . .
- hybrid MC/MD (not very good)

Programming tricks:

- cache
- nearest neighbors in periodic boundary conditions
- tables: pair potential calculated by splines

Parallel code:

- usually based on domain decomposition (linked-cell list)
- standard computers 4–32 cores
- Graphics Processing Units: thousands of processors, more difficult to program

*s*12/2

Kinetic quantities: EMD nd NEMD

Kinetic quantities: diffusivity, electric conductivity, viscosity, heat conductivity

Nonequilibrium molecular dynamics (NEMD)

- as in "real experiment" field or perturbation added (electric field, thermal gradient, shear stress)
- dissipation heat is generated \Rightarrow good thermostat needed
- dissipation extrapolation to zero perturbation
- **SLODD**

Equilibrium molecular dynamics (EMD)

- one equilibrium simulation enough
- based on the Linear Response Theory Green–Kubo: $D = \frac{1}{3} \int_{0}^{\infty} \langle \dot{\vec{r}}_{i}(t) \cdot \dot{\vec{r}}_{i}(0) \rangle dt$ Einstein: $2tD = \frac{1}{3} \langle |\vec{r}_i(t) - \vec{r}_i(0)|^2 \rangle$

$$D = \frac{1}{3} \int_0^\infty \langle \dot{\vec{r}}_i(t) \cdot \dot{\vec{r}}_i(0) \rangle dt$$