Parallel paradigm

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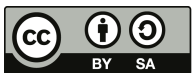
EVROPSKÁ UNIE
Evropské strukturální a investiční fondy
Operační program Výzkum, vývoj a vzdělávání

MINISTERSTVO ŠKOLSTVÍ, MLÁDEŽE A TĚLOVÝCHOVY



Overview

- Programming background
- Memory
- Building blocks
- Conclusion

Hello programming

C

- Dennis Ritchie at 1972
- GP, procedural, imperative, statically typed
- direct memory control
- standardized *(current C17)*

C++

- Bjarme Stroustrup at 1985
- add OOP & functional
- standardized *(current C++20)*

CUDA

- Nvidia at 2007
- parallel computing platform, API to GPU, scalable *(across GPU)*
- works with C, C++, Fortran
- control of GPU from CPU *(not full)*
- new device memory space
- one code $\rightarrow$ split compilation for CPU/GPU
- dedicated libraries *(cuBLAS, cuFFT,cuRAND ...)*

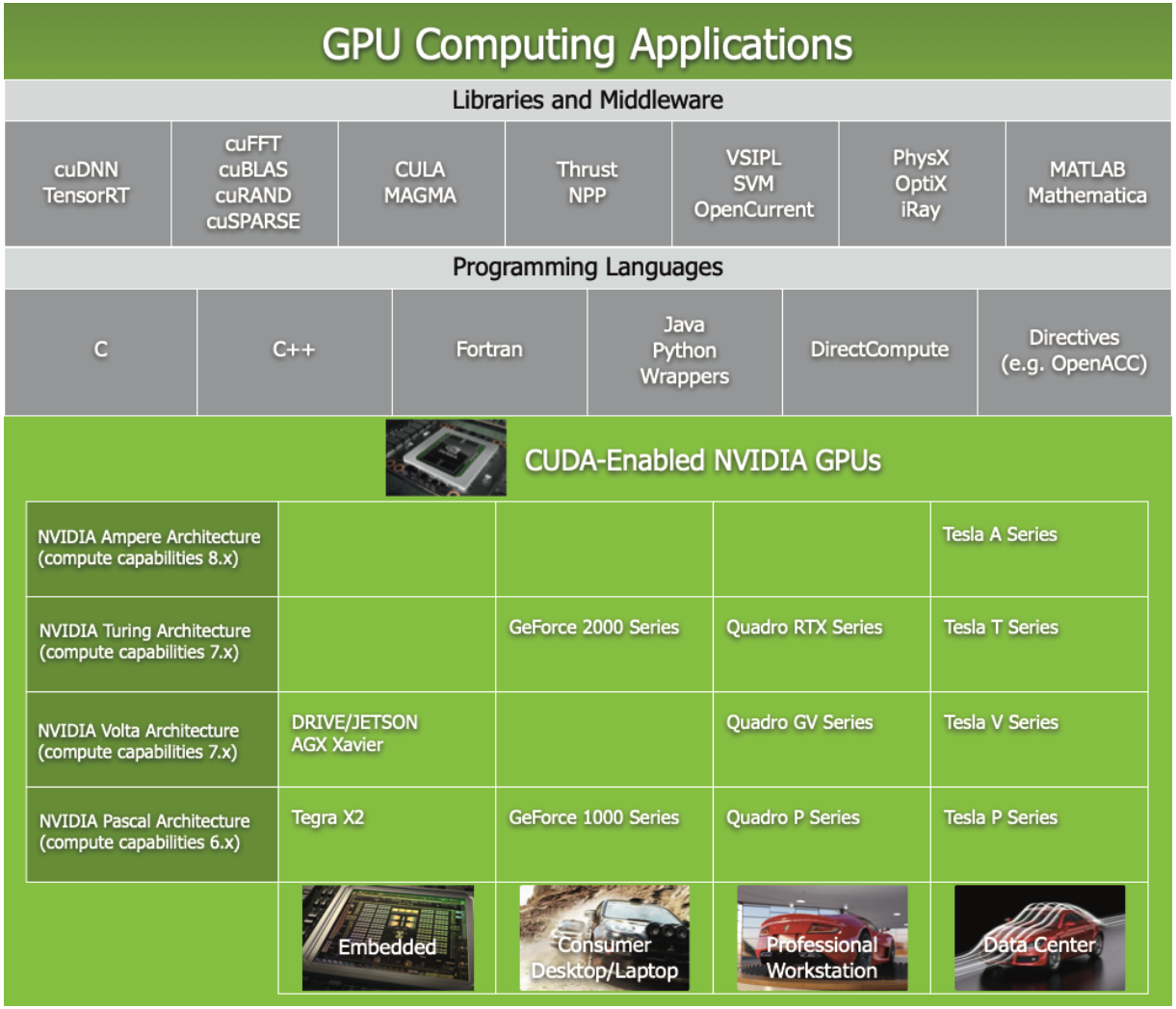


Figure: Look at the GPU specialization on different tasks. @ docs.nvidia.com

```
#include <stdio.h>
__global__ void hello_kernel()
{
    int thread_id = (blockDim.x*blockIdx.x + threadIdx.x);
    printf("Hello, World from thread: %d\n", thread_id);
}

int main ()
{
    hello_kernel<<<1,1>>>();
    \\ hello_kernel<<<1,48>>>(); \\ What happens here?
    \\ hello_kernel<<<4,12>>>(); \\ And here ?
    cudaDeviceSynchronize();
    return 0;
}
```

- multiple memory levels, caches
- specialized types *(constant, texture)*
- **high latency** require tricks *(multidispatch, swap)*
- memory **sensitive to coalesced access**
- adjustable caching ability *(L1 vs Shared mem.)*
- access pattern heavily influence efficiency

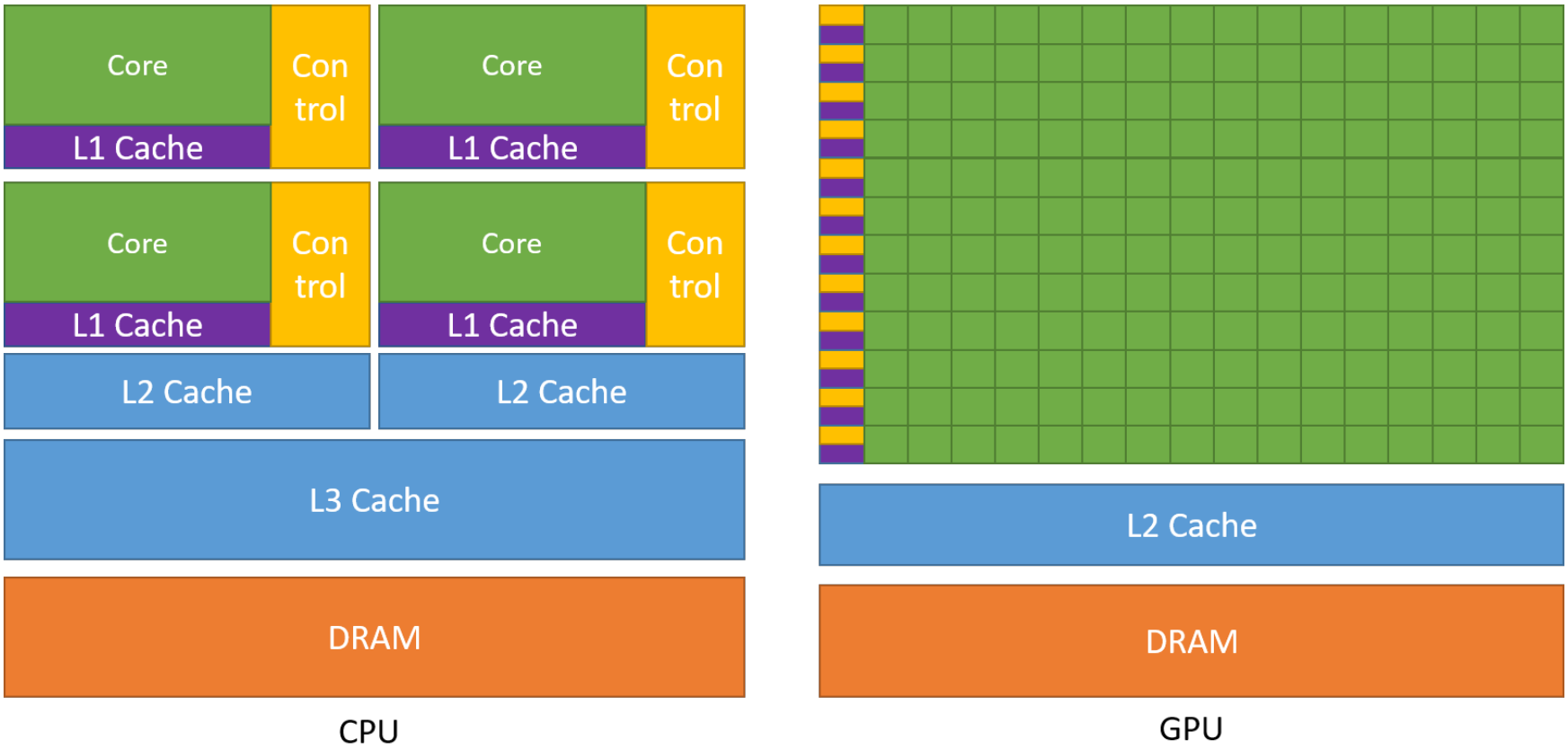


Figure: Schematical comparison of CPU/GPU memory spaces and cores.
@ docs.nvidia.com

New memory playground

Type	**Size** *(deviceQuery)*	**Latency** *(rule of thumb)*
1. RAM	1. 2GB - 64GB	1. 800-1000 x *(or more)*
2. global mem.	2. 1GB - 24GB*	2. 80-120 x
3. shared mem. *(cache)*	3. 64, 128kB*	3. 7-12 x
4. constant mem.	4. 32, 48, 64kB*	4. 6-10 x *(readonly)*
5. local mem. *(registers)*	5. 64kb for all threads	5. 1

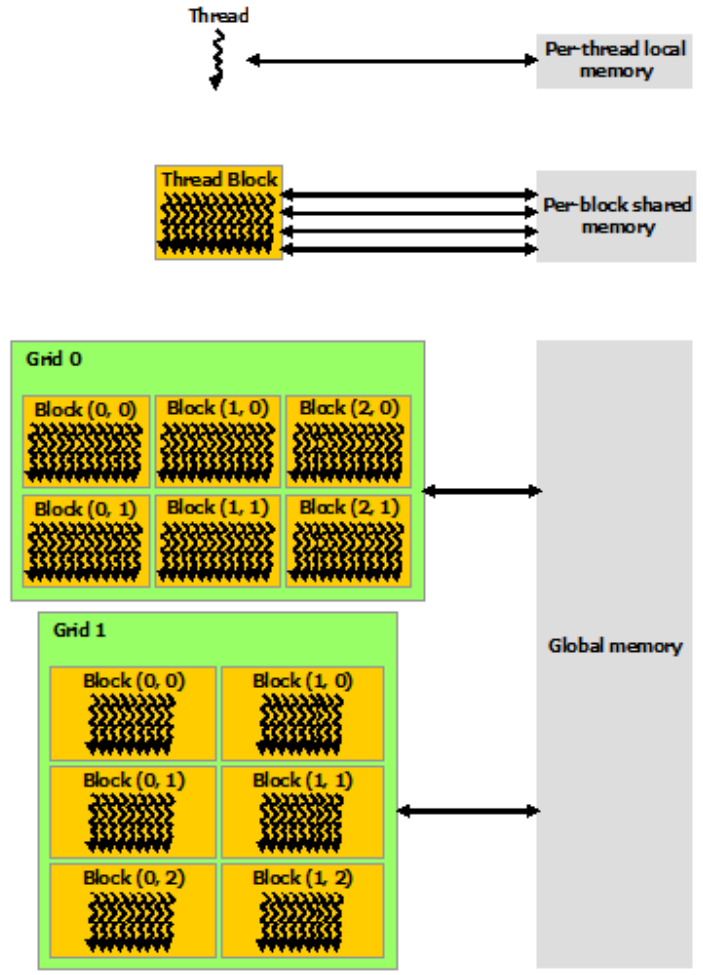
Operational groups

residence

1. core
2. SM
3. GPU
4. multiGPU

code specification

1. <<<?, # **threads** >>>
2. <<< # **blocks**, ? >>>
3. <<<?, ? >>>
4. <<<?, ?, ?, **stream #** >>>



thread

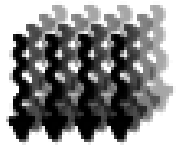
- the smallest unit
- occupy single core
- located by threadIdx *(x,y,z)*
- use registers/local memory for storage
- can't communicate directly with other threads
- synchronized by *__syncthreads()*

block

- group of threads
- run concurrently *(up to 32, divergence)*
- located by blockIdx *(x,y,z)*
- size determined by blockDim *(x,y,z)*
- use shared memory for storage/communication within block
- isolated from other blocks

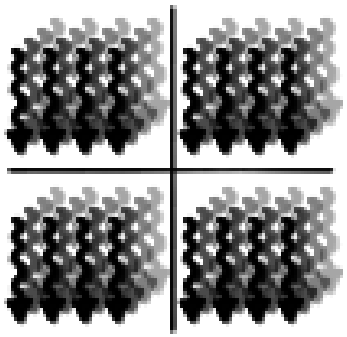
warp

- 32 threadblock *(halfwarp)*
- scheduled for evaluation *(max group)*



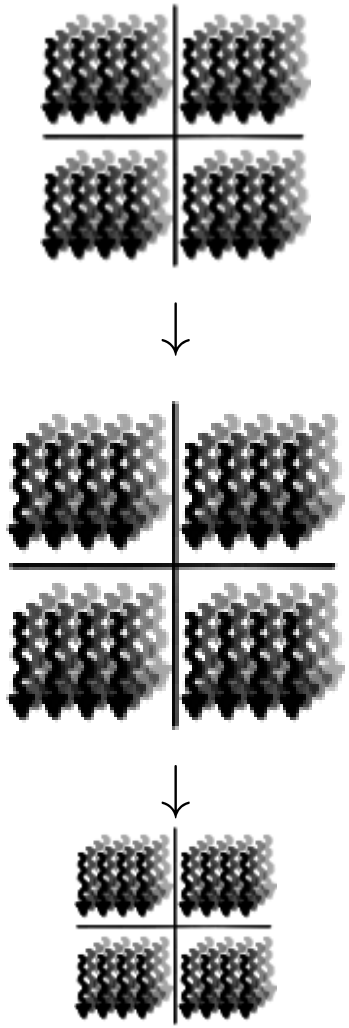
grid

- lattice of blocks
- occupy device *(stream on device)*
- dimension available in gridDim *(x,y,z)*
- use global memory for communication
- no precise control how it is distributed on device
- implicit synchronization at the end of kernel



stream

- flow of kernel launches with same purpose
- default stream, other require prior initialization
- can be multiple on single device
- utilize available resources *(priorities)*
- way how to parallelize on multiple GPU
- use global memory for communication
- explicit synchronization with *cudaStreamSynchronize()*



Summary

- what we work with
- memory is the key to speed
  - different types of it
- building blocks of program
  - and its hierarchy

References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- until next time image [Cit. 02.09.2021]. Available from https:\\i.chzbgr.com\full\9591931648\hDC02ACF7\person-my-hacky-program-cpu-o-other-7-processor-cores-my-rtx-3090

Practical session

1. start/setup your development tool
2. get the source code
3. follow the **instructions in code**
   - if unsure → first think about it
   - if still lost → "google" it
   - if can't find → ask about it *(personally or mail)*
4. make sure your code **compiles**
5. make sure your code **works**
6. send your code to me *(celnyd@vscht.cz)*

Until next time