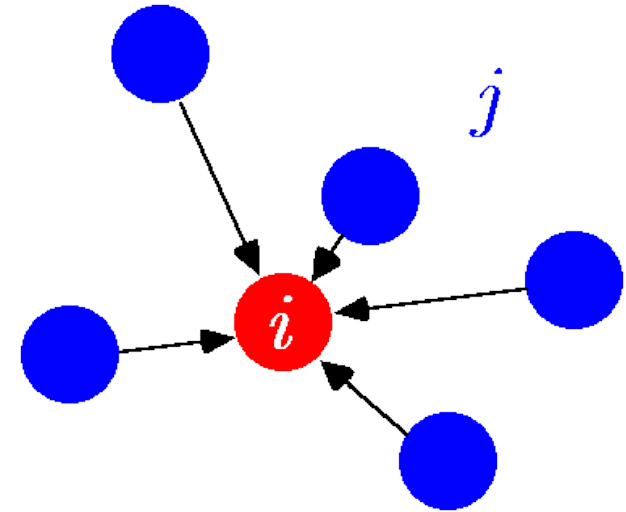


- hard spheres etc. – collisions
- “classical” MD – integration of the equations of motion
- Brownian (stochastic) dynamics, dissipative particle dynamics = MD + random forces

**Forces** are needed:

$$\vec{f}_i = -\frac{\partial U(\vec{r}^N)}{\partial \vec{r}_i} \quad i = 1, \dots, N$$



Example – pair forces:

$$U = \sum_{i < j} u(r_{ij}) \quad \Rightarrow \quad \vec{f}_i = \sum_{\substack{j=1 \\ j \neq i}}^N \vec{f}_{ji} \equiv - \sum_{\substack{j=1 \\ j \neq i}}^N \frac{du(r_{ji})}{dr_{ji}} \frac{\partial r_{ji}}{\partial \vec{r}_i} = - \sum_{\substack{j=1 \\ j \neq i}}^N \frac{du(r_{ji})}{dr_{ji}} \frac{\vec{r}_{ji}}{r_{ji}}$$

Notation:  $\vec{r}_{ij} = \vec{r}_j - \vec{r}_i$ ,  $r_{ij} = |\vec{r}_{ij}|$

$$\frac{d^2 \vec{r}_i}{dt^2} = \ddot{\vec{r}}_i = \frac{\vec{f}_i}{m_i}, \quad i = 1, \dots, N$$

Method of finite differences, timestep  $h$

Initial value problem:  $\vec{r}$  and  $\dot{\vec{r}}$  at time  $t_0$  are known

## Methods:

- Runge–Kutta: many evaluations of the right-hand side/step (costly!)
- Predictor–corrector: a bit better, rarely used
- Verlet and clones (symplectic = good energy conservation)
- Multiple timestep methods: more timescales (usually symplectic)
- Geometric integrators (symplectic)

Taylor expansion:

$$\begin{aligned}\vec{r}_i(t-h) &= \vec{r}_i(t) - h\dot{\vec{r}}_i(t) + \frac{h^2}{2}\ddot{\vec{r}}_i(t) - \dots && +1\times \\ \vec{r}_i(t) &= \vec{r}_i(t) && -2\times \\ \vec{r}_i(t+h) &= \vec{r}_i(t) + h\dot{\vec{r}}_i(t) + \frac{h^2}{2}\ddot{\vec{r}}_i(t) + \dots && +1\times\end{aligned}$$

$\Rightarrow$  numeric 2nd derivative:  $\ddot{\vec{r}}_i(t) = \frac{\vec{f}_i(t)}{m_i} = \frac{\vec{r}_i(t-h) - 2\vec{r}_i(t) + \vec{r}_i(t+h)}{h^2} + \mathcal{O}(h^2)$

Verlet method:  $\vec{r}_i(t+h) = 2\vec{r}_i(t) - \vec{r}_i(t-h) + h^2 \frac{\vec{f}_i(t)}{m_i}$

Initial values:  $\vec{r}_i(t_0-h) = \vec{r}_i(t_0) - h\dot{\vec{r}}_i(t_0) + \frac{h^2}{2} \frac{\vec{f}_i(t_0)}{m_i} + \mathcal{O}(h^3)$

⊕ time-reversible ( $\Rightarrow$  no energy drift); even symplectic

⊖ cannot use for  $\ddot{r} = f(r, \dot{r})$  because  $\dot{r}(t)$  is not known at time  $t$

Identical trajectories: leap-frog, velocity Verlet, Gear ( $m = 3$ ), Beeman

# Leap-frog

velocity = displacement (change in position) per unit time  $h$  (vector)

$$\vec{v}(t + h/2) = \frac{\vec{r}(t + h) - \vec{r}(t)}{h}$$

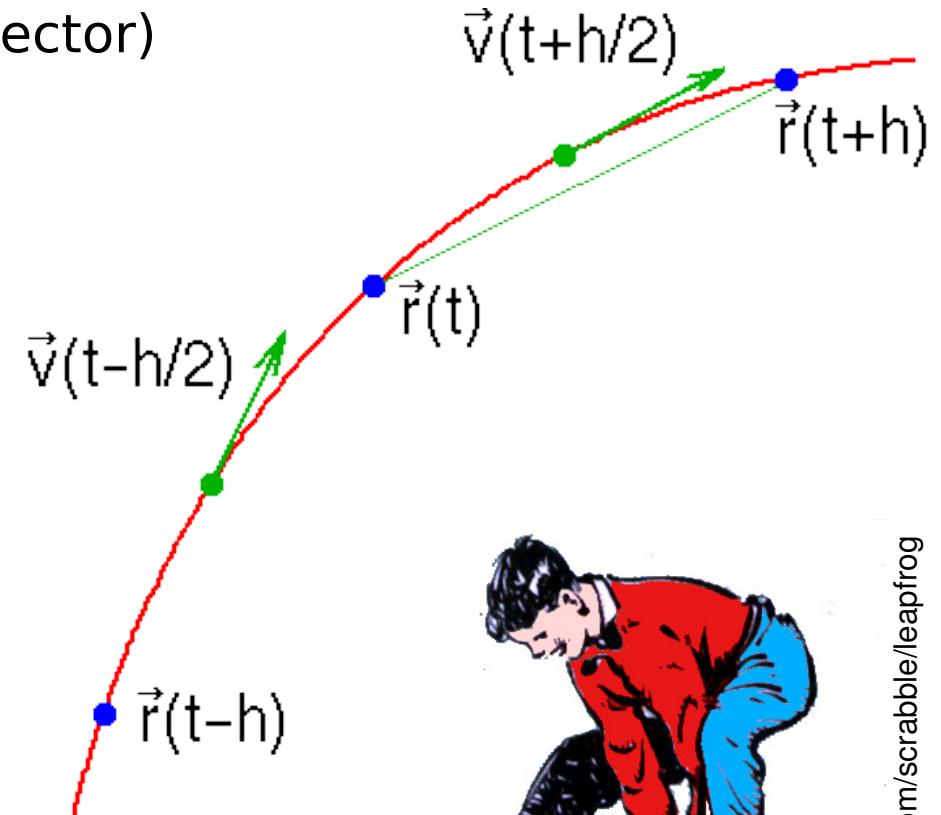
acceleration = change in velocity per unit time

$$\vec{a}(t) = \frac{\vec{v}(t + h/2) - \vec{v}(t - h/2)}{h} = \frac{\vec{f}}{m}$$

⇒

$$\left. \begin{aligned} \vec{v}(t + h/2) &:= \vec{v}(t - h/2) + \vec{a}(t)h \\ \vec{r}(t + h) &:= \vec{r}(t) + \vec{v}(t + h/2)h \\ t &:= t + h \end{aligned} \right\} \text{repeated}$$

- equivalent to Verlet (identical trajectory)  
but: velocities at different time, a bit different (by  $\mathcal{O}(h^2)$ ) kinetic energy



Leap-frog:

$$\left. \begin{aligned} v(t + h/2) &:= v(t - h/2) + a(t)h \\ r(t + h) &:= r(t) + v(t + h/2)h \\ t &:= t + h \end{aligned} \right\} \text{repeated}$$

2nd equation twice in 2 different times:

$$\begin{aligned} r(t + h) &= r(t) + v(t + h/2)h && \times + 1 \\ r(t) &= r(t - h) + v(t - h/2)h && \times - 1 \end{aligned}$$

Subtract both equations:

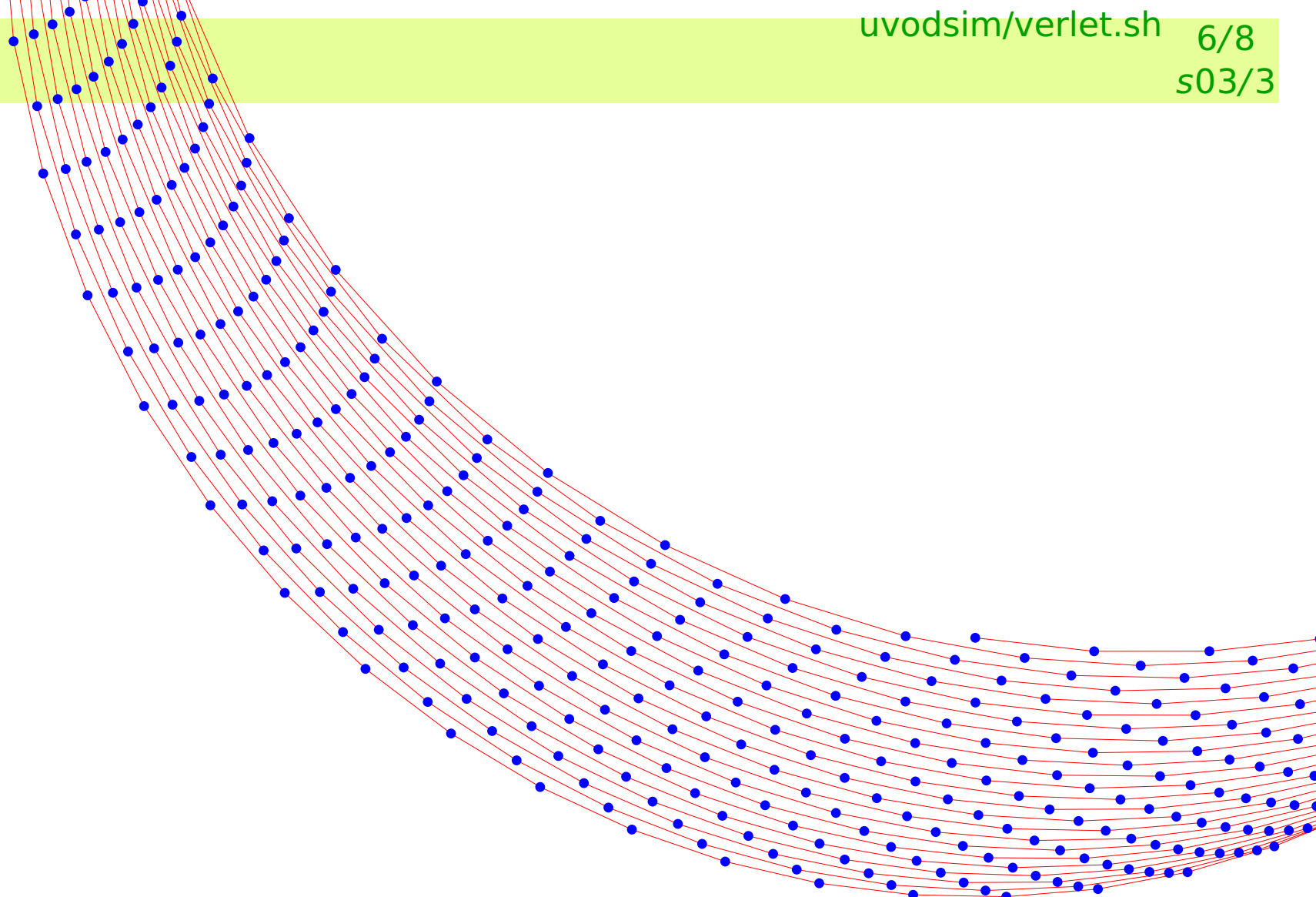
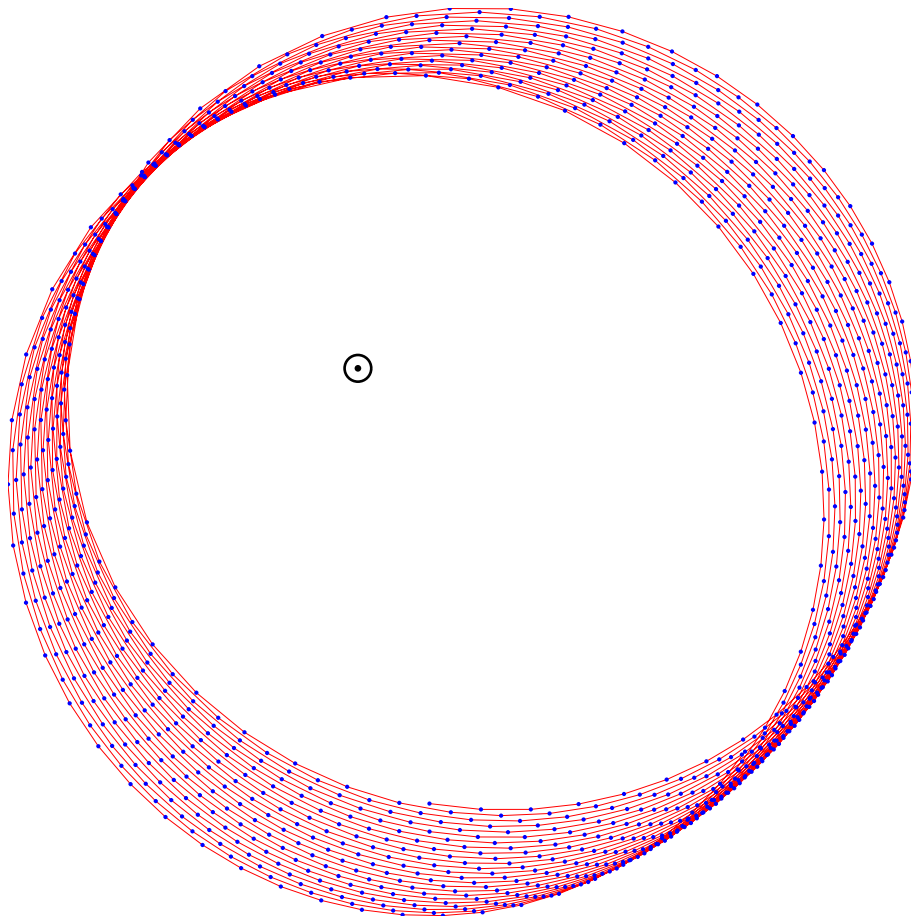
$$r(t + h) - r(t) = r(t) - r(t - h) + v(t + h/2)h - v(t - h/2)h$$

insert for the difference of velocities:

$$r(t + h) - 2r(t) + r(t - h) = h[v(t + h/2) - v(t - h/2)] = a(t)h^2 = \frac{f(t)}{m}h^2$$

which is the Verlet method

# Example: planetary orbit



- energy is well conserved
- perihelion precession  $\mathcal{O}(h^2)$
- harmonic oscillator: frequency shifted  $\mathcal{O}(h^2)$

By methods of theoretical mechanics:

- expressing the position and momentum propagators in operator form
- some tricks to overcome their noncommutativity

we can derive the **velocity Verlet**:

$$r(t+h) = r(t) + v(t)h + \frac{f(t)h^2}{m} \frac{1}{2}$$
$$v(t+h) = v(t) + \frac{f(t) + f(t+h)h}{m} \frac{1}{2}$$

The same trajectory as Verlet with  $v(t) = \frac{r(t+h) - r(t-h)}{2h} \dots$

kinetic energy differs from leap-frog by  $\mathcal{O}(h^2)$

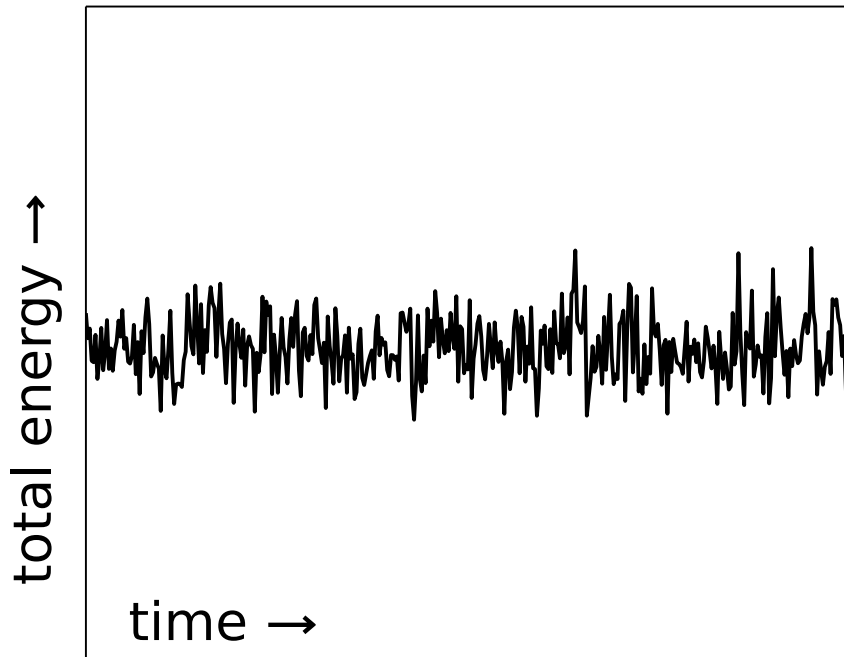
... but we can also learn a lot about energy conservation

# What is this good for?

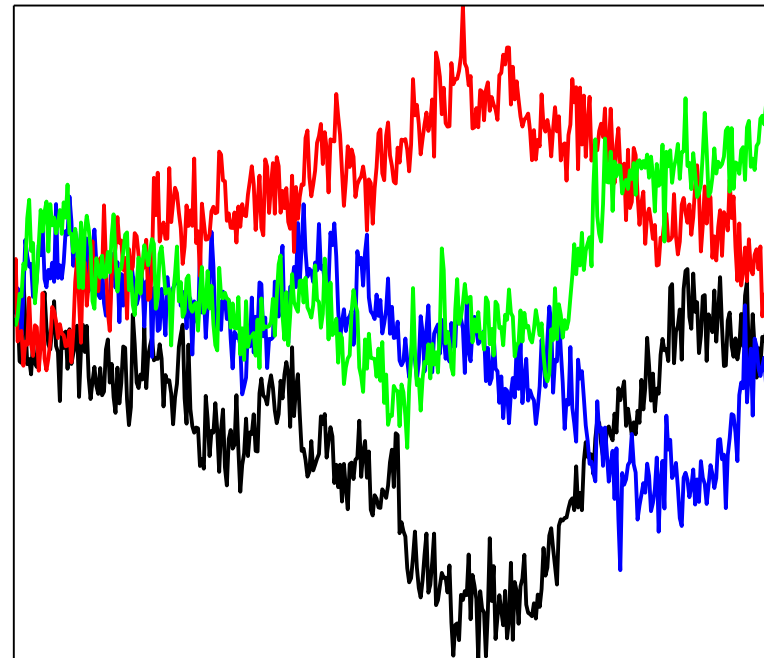
$$\exp(i\hat{L}_p h/2) \exp(i\hat{L}_r h) \exp(i\hat{L}_p h/2) = \exp(i\hat{L}h + \epsilon)$$

- error  $\epsilon$  can be estimated ( $\propto h^3$ )
- we can calculate a “perturbed Hamiltonian” (error  $\mathcal{O}(h^3)$  per step,  $\mathcal{O}(h^2)$  globally), exactly constant with the Verlet method  
i.e., Verlet is **symplectic**  $\Rightarrow$  error is bound  
(time reversibility  $\Rightarrow$  only error  $\propto t^{1/2}$ )
- multiple-timestep methods and higher-order methods

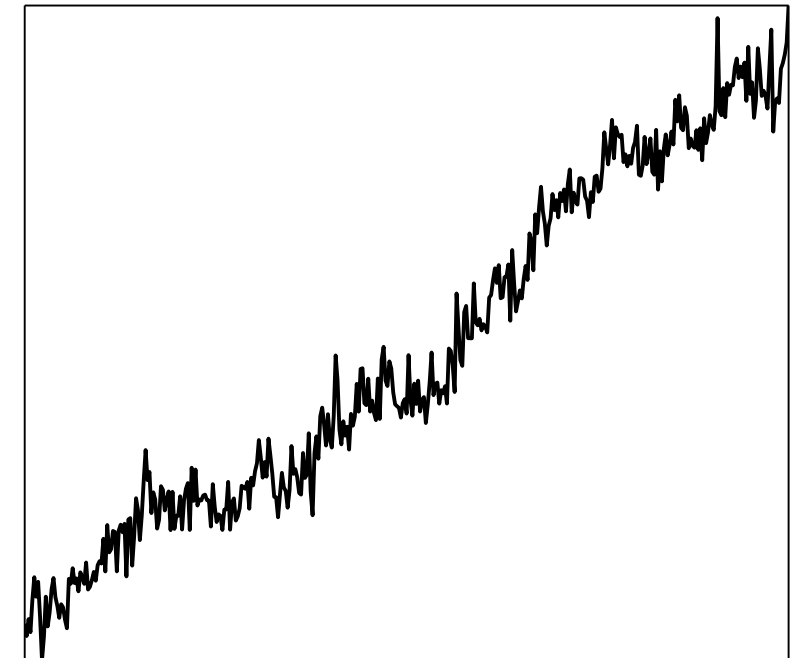
energy conservation error is used to set the timestep  $h$



symplectic



reversible



irreversible