

```

PDEParabImplPC := proc (n, m, k, a, b, g, e, f, alfa1, beta1, alfa2, beta2, gama1, gama2, phi)
  local h, n1, m1, u, i, j, alfa, beta, x, F, d1, d2, d3, p, q, r, s, pom, up, df, v;
  with(linalg);
  h := (b-a)/n;
  n1 := n + 1;
  m1 := m + 1;
  alfa := evalf(k/(h*h));
  beta := evalf(k/(2*h));
  df := D[3](f);
  x := Vector(n1, i → a + (i-1)*h);
  u := Matrix((m1, n1), 0);
  d1 := Vector(n1, 0);
  d2 := Vector(n1, 0);
  d3 := Vector(n1, 0);
  F := Vector(n1, 0);
  v := Vector(n1, 0);
  #výpo et profilu u - 0 vrstva
  for i from 1 to n1 do
    u[1, i] := evalf(phi(x[i]));
  end do;
  #Výpo et diagonál v matici A a pravé strany, u(j+1)=F(j)+A*u(j)
  for j from 1 to m do
    #výpo et pomocného profilu v pomoci expl. metody - predictor
    for i from 1 to n1 do
      d1[i] := evalf(g(x[i], (j-1)*k)*alfa-e(x[i], (j-1)*k)*beta);
      d2[i] := evalf(1-2*alfa*g(x[i], (j-1)*k));
      d3[i] := evalf(g(x[i], (j-1)*k)*alfa+e(x[i], (j-1)*k)*beta);
      F[i] := evalf(k*f(x[i], (j-1)*k, u[j, i]));
    end do;
    for i from 2 to n do
      v[i] := evalf(F[i]+d1[i]*u[j, i-1]+d3[i]*u[j, i+1]+d2[i]*u[j, i])
    end do;
    # výpo et j+1-ního profilu pomocí implicitní metody - corrector
    # napo útání diagonál matice pravé strany
    for i from 1 to n-1 do
      d1[i] := -evalf(g(x[i+1], j*k)*alfa-e(x[i+1], j*k)*beta);
      d2[i] := evalf(1+2*alfa*g(x[i+1], j*k)-k*df(x[i+1], j*k, u[j, i+1]));
      d3[i] := -evalf(g(x[i+1], j*k)*alfa+e(x[i+1], j*k)*beta);
      F[i] := evalf(u[j, i+1]+k*f(x[i+1], j*k, v[i+1]));
    end do;
    # Dosezení okrajových podmínek do první a poslední rovnice
    p := 1/(alfa1*2*h-3*beta1(j*k));
    r := beta1(j*k)*p;
    pom := d1[1]*r;
    d2[1] := d2[1]-4*pom;
    d3[1] := d3[1]+pom;
    F[1] := F[1]-2*h*gama1(j*k)*d1[1]*p;
    q := 1/(alfa2*2*h+3*beta2(j*k));
    s := beta2(j*k)*q;
    pom := d3[n-1]*s;
    d2[n-1] := d2[n-1]+4*pom;
    d1[n-1] := d1[n-1]-pom;

```

```

F[n-1] := F[n-1]-2*h*gama2(j*k)*d3[n-1]*q;
up := TriDiagonalSolve(n-1, d1, d2, d3, F);
for i from 2 to n do
    u[j+1, i] := up[i-1];
end do;
# výpo et okrajových podmínek - j+1 vrstva, tj. pro t=j*k
u[j+1, 1] := 2*h*gama1(j*k)*p-r*(4*u[j+1, 2]-u[j+1, 3]);
u[j+1, n1] := 2*h*gama2(j*k)*q+s*(4*u[j+1, n]-u[j+1, n-1]);
end do;
RETURN(eval(u));
end proc:

```

## ▼ Příklad 1:

```

phi := x → sin(evalf(Pi*x)) :
alfa1 := 1 :
beta1 := t → 0 :
alfa2 := 1 :
beta2 := t → 0 :
gama1 := t → 0 :
gama2 := t → 0 :
g := (x, t) → 1 :
e := (x, t) → 0 :
f := (x, t, y) → 0 :
n := 10 :
m := 80 :
k := 0.005 :
h :=  $\frac{1.0}{n}$ ;
T := k*m;

```

0.1000000000

0.400

(1.1)

```
vys := PDEParabImplPC(n, m, k, 0.0, 1.0, g, e, f, alfa1, beta1, alfa2, beta2, gama1, gama2, phi);
```

[
  
*81 x 11 Matrix*
  
*Data Type: anything*
  
*Storage: rectangular*
  
*Order: Fortran\_order*
  
]

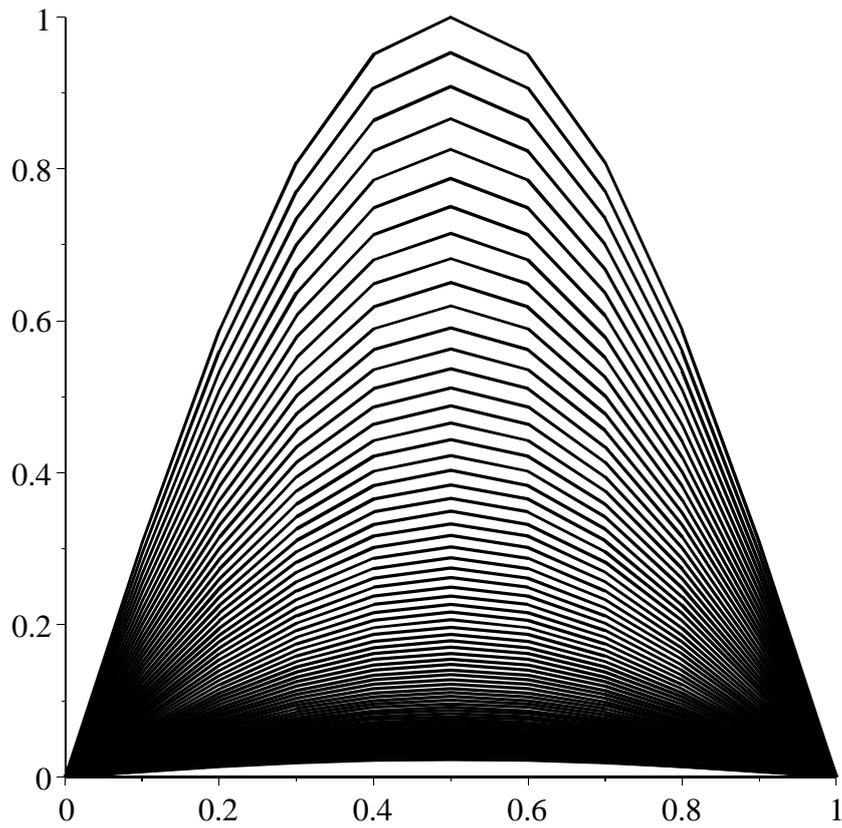
(1.2)

```

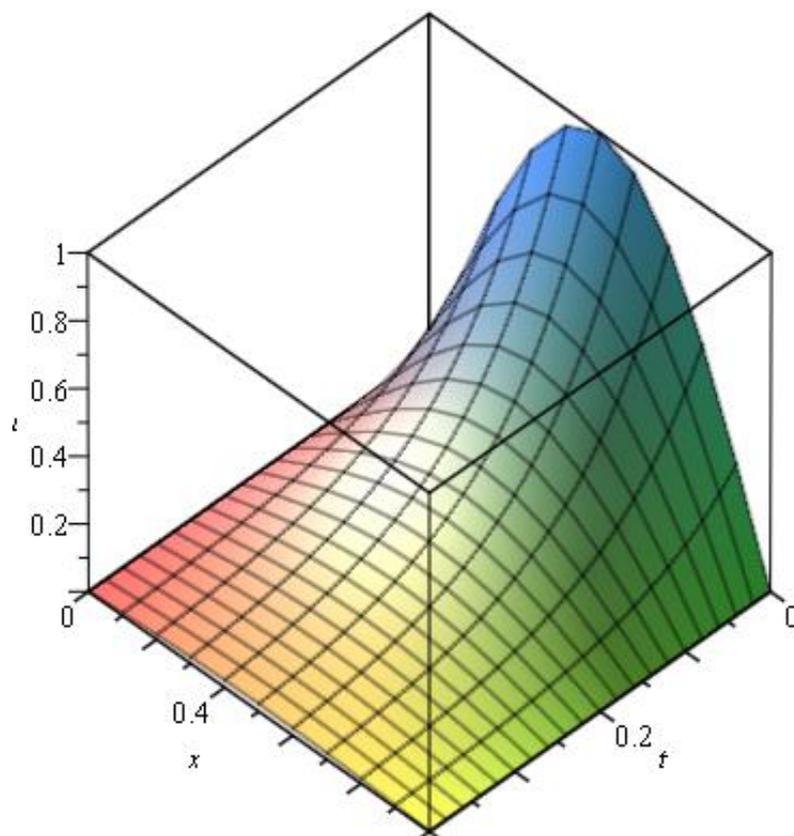
data := [seq([seq([0 + (i-1)*h, vys[j, i]], i=1..n+1)], j=1..m+1)]:
with(plots) :

```

```
display(seq(listplot(data[i]), i=1..m));
```



```
a := subs(1 .. m + 1 = 0 .. T, 1 .. n + 1 = 0 .. 1, matrixplot(vys[1 .. m + 1, 1 .. n + 1], labels = [t,
x, u])) :
display(a, view = [0 .. T, 0 .. 1, 0 .. 1]);
```



## ► P íklad 2:

$\text{phi} := x \rightarrow 1 - x \cdot x :$

$\text{alfa1} := 1 :$

$\text{beta1} := t \rightarrow 0 :$

$\text{alfa2} := 1 :$

$\text{beta2} := t \rightarrow 0 :$

$\text{gama1} := t \rightarrow 1 :$

$\text{gama2} := t \rightarrow 0 :$

$g := (x, t) \rightarrow 1 :$

$e := (x, t) \rightarrow 1 :$

$f := (x, t, y) \rightarrow -\exp(-y) :$

$n := 10 :$

$m := 50 :$

$k := 0.005 :$

$h := \frac{1.0}{n} ;$

$T := k \cdot m ;$

0.1000000000

0.250

(2.1)

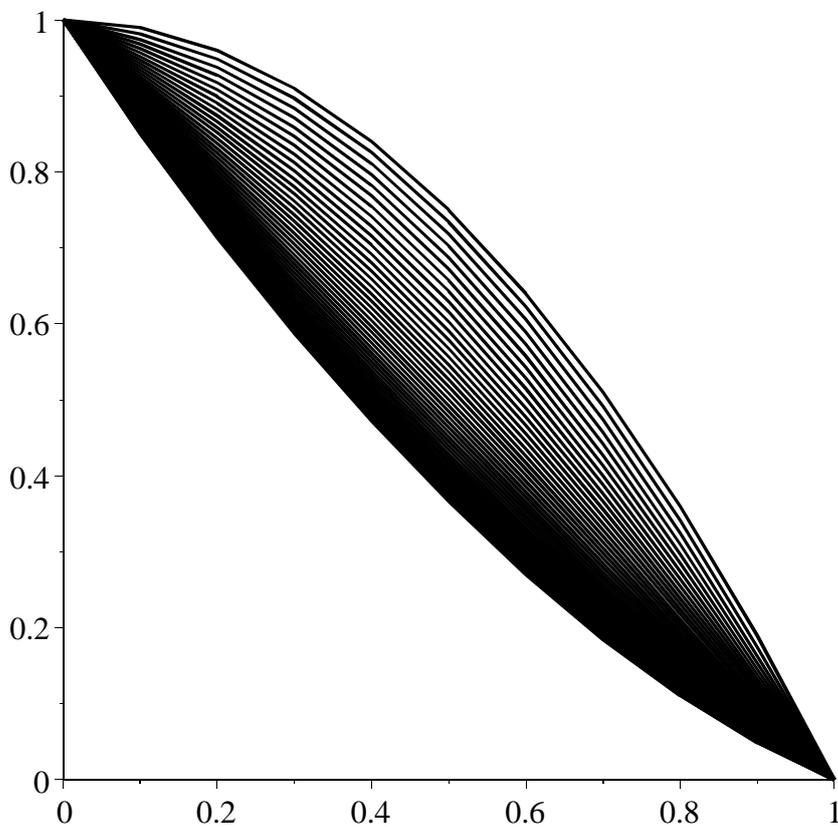
```
vys := PDEParabImplPC(n, m, k, 0.0, 1.0, g, e, f, alfa1, beta1, alfa2, beta2, gama1, gama2, phi);
```

*51 x 11 Matrix*  
*Data Type: anything*  
*Storage: rectangular*  
*Order: Fortran\_order*

(2.2)

```
data := [seq([seq([0 + (i - 1) · h, vys[j, i]], i = 1 .. n + 1)], j = 1 .. m + 1)]:  
with(plots):
```

```
display(seq(listplot(data[i]), i = 1 .. m));
```



```
a := subs(1 .. m + 1 = 0 .. T, 1 .. n + 1 = 0 .. 1, matrixplot(vys[1 .. m + 1, 1 .. n + 1], labels = [t,  
x, u])) :  
display(a, view = [0 .. T, 0 .. 1, 0 .. 1]);
```

