

[> **read "DESite.m":**

Apl. p íklad 1:

Izotermní vnitní difuze v porézním katalyzátoru je popsána diferenciální rovnicí

$$y'' + a/x \cdot y' = \phi^2 \cdot y^n$$

Parametr a charakterizuje tvar ástice katalyzátoru: $a=0$ pro desku, $a=1$ pro váleček, $a=2$ pro kuličku, n je rád reakce a Thieleho modul.

- a) Vyřešte tuto rovnici metodou sítí pro $n=0$, $a=1$ a $\phi=1$
- b) Vyřešte tuto rovnici metodou sítí pro $n=1$, $a=2$ a $\phi=1;2;4$
- c) Vyřešte tuto rovnici metodou sítí pro $n=1$, $a=0$ a $\phi=1;2;4$

▼ a)

Definice parametrů diferenciální rovnice

Lineární rovnice

```
> n1:=0:
      aa:=1:
      phi:=1:
```

Definice pravé strany diferenciální rovnice

```
> f:=(x,y,dy)->-aa/x*dy + phi^2*y^n1;
```

$$f := (x, y, dy) \rightarrow -\frac{aa \cdot dy}{x} + \phi^2 \cdot y^{n1} \quad (1.1)$$

Definice parametrů metody

```
> a := 0:
      b := 1:
      alfa1 := 0:
      alfa2 := 1:
      beta1 := 1:
      beta2 := 0:
      gama1 := 0:
      gama2 := 1:
      eps := 0.1e-3:
      n := 20:
      y0:=evalf([seq(0.5,i=1..n+1)]):
      y0[1]:=1.0;
      y0[n+1]:=1.0;
y0:=[0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5]
```

$y_{01} := 1.0$

$y_{021} := 1.0$

(1.2)

```
> yres := DESite2(n,f,a, b,alfa1,alfa2,beta1,beta2,gama1,
      gama2, eps, y0, 10):
      "iterace = ", 0
"y = ", [0.5000000000, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5]
      "iterace = ", 1, "    s = ", 0.6112373246
"y = ", [0.7499999996, 0.7506249997, 0.7524999997, 0.7556249997, 0.7599999997,
      0.7656249997, 0.7724999997, 0.7806249997, 0.7899999997, 0.8006249997,
      0.8124999997, 0.8256249997, 0.8399999997, 0.8556249997, 0.8724999997,
      0.8906249997, 0.9099999997, 0.9306249997, 0.9524999997, 0.9756249997, 1.]
```

```

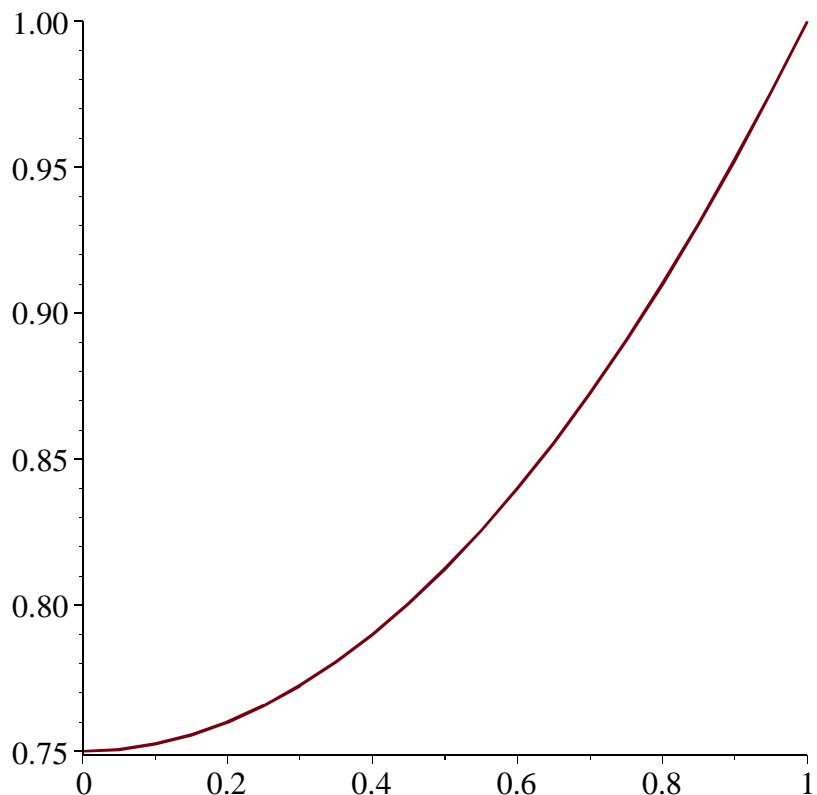
"iterace = ", 2, "    s = ", 3.501912068 10-8
"y = ", [0.7500000399, 0.7506250397, 0.7525000395, 0.7556250390, 0.7600000383,
          0.7656250374, 0.7725000363, 0.7806250350, 0.7900000335, 0.8006250319,
          0.8125000300, 0.8256250279, 0.8400000256, 0.8556250231, 0.8725000204,
          0.8906250175, 0.9100000144, 0.9306250111, 0.9525000076, 0.9756250039, 1.]

```

```

> # Graf funkce yres(x)
> plot(yres);

```



```

> # Tabulka hodnot funkce y(x)
> linalg[matrix](yres);

```

	0.	0.7500000399	(1.4)
	0.050000000000	0.7506250397	
	0.100000000000	0.7525000395	
	0.150000000000	0.7556250390	
	0.200000000000	0.7600000383	
	0.250000000000	0.7656250374	
	0.300000000000	0.7725000363	
	0.350000000000	0.7806250350	
	0.400000000000	0.7900000335	
	0.450000000000	0.8006250319	
	0.500000000000	0.8125000300	
	0.550000000000	0.8256250279	
	0.600000000000	0.8400000256	
	0.650000000000	0.8556250231	
	0.700000000000	0.8725000204	
	0.750000000000	0.8906250175	
	0.800000000000	0.9100000144	
	0.850000000000	0.9306250111	
	0.900000000000	0.9525000076	
	0.950000000000	0.9756250039	
	1.0000000000	1.	

b)

Definice parametr diferenciální rovnice

```
> n1:=1:  
aa:=2:  
phi:=1:
```

Definice pravé strany diferenciální rovnice

```
> f:=(x,y,dy)->-aa/x*dy + phi^2*y^n1 ;  
f:=(x,y,dy)→ -  $\frac{aa\ dy}{x} + \phi^2 y^{n1}$ 
```

(2.1)

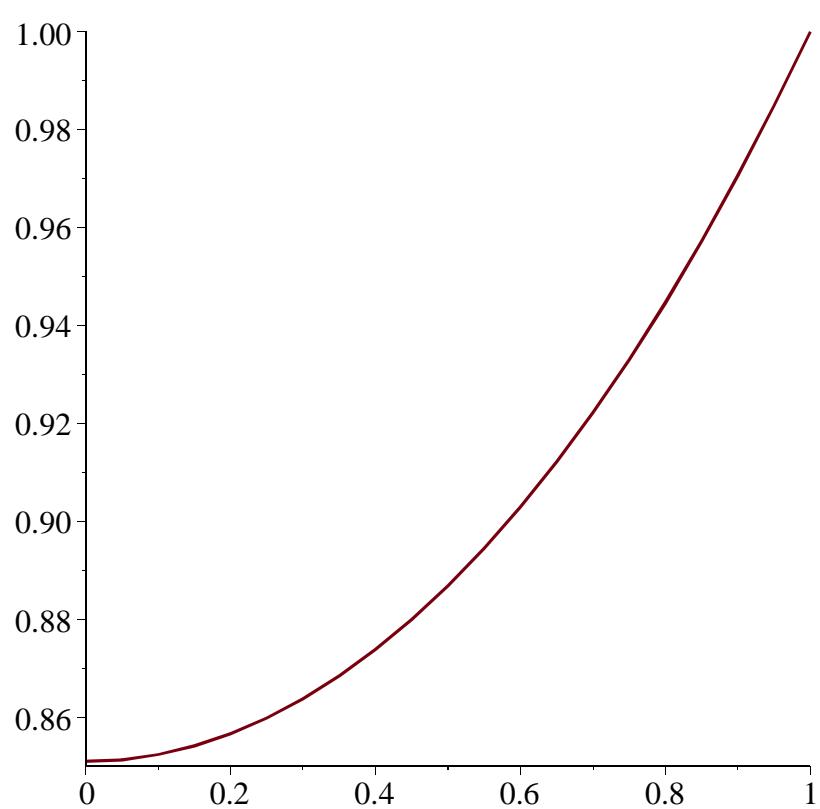
Definice parametr metody

```
> a := 0:  
b := 1:  
alfa1 := 0:  
alfa2 := 1:  
beta1 := 1:  
beta2 := 0:  
gama1 := 0:  
gama2 := 1:  
eps := 0.1e-5:  
n := 20:
```

```

y0:=evalf([seq(0.8,i=1..n+1)]);
y0[1]:=1.0;
y0[n+1]:=1.0;
y0:=[0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8,0.8]
y01:=1.0
y021:=1.0
> yres := DESite2(n,f,a, b, alfa1, alfa2, beta1, beta2, gama1,
gama2, eps, y0, 10):
"iterace = ", 0
"y = ", [0.7999999999, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8]
"iterace = ", 1, " s = ", 0.1260824218
"y = ", [0.8509456896, 0.8513003979, 0.8523645234, 0.8541398394, 0.8566290097,
0.8598357698, 0.8637649344, 0.8684224054, 0.8738151826, 0.8799513763,
0.8868402219, 0.8944920961, 0.9029185356, 0.9121322581, 0.9221471843,
0.9329784638, 0.9446425016, 0.9571569879, 0.9705409298, 0.9848146852, 1.]
"iterace = ", 2, " s = ", 4.234082026 10-9
"y = ", [0.8509456839, 0.8513003924, 0.8523645180, 0.8541398342, 0.8566290046,
0.8598357646, 0.8637649294, 0.8684224007, 0.8738151784, 0.8799513723,
0.8868402185, 0.8944920932, 0.9029185331, 0.9121322555, 0.9221471816,
0.9329784613, 0.9446424997, 0.9571569864, 0.9705409287, 0.9848146849, 1.]
> # Graf funkce y(x)
> plot(yres);

```



```
> # Tabulka hodnot funkce y(x)
> linalg[matrix](yres);
```

(2.4)

0.	0.8509456839	
0.05000000000	0.8513003924	
0.10000000000	0.8523645180	
0.15000000000	0.8541398342	
0.20000000000	0.8566290046	
0.25000000000	0.8598357646	
0.30000000000	0.8637649294	
0.35000000000	0.8684224007	
0.40000000000	0.8738151784	
0.45000000000	0.8799513723	
0.50000000000	0.8868402185	(2.4)
0.55000000000	0.8944920932	
0.60000000000	0.9029185331	
0.65000000000	0.9121322555	
0.70000000000	0.9221471816	
0.75000000000	0.9329784613	
0.80000000000	0.9446424997	
0.85000000000	0.9571569864	
0.90000000000	0.9705409287	
0.95000000000	0.9848146849	
1.000000000	1.	

Definice parametr diferenciální rovnice

```
> n1:=1:  
aa:=2:  
phi:=2:
```

Definice pravé strany diferenciální rovnice

```
> f:=(x,y,dy)->-aa/x*dy + phi^2*y^n1 ;
f:=(x,y,dy) → -  $\frac{aa \, dy}{x} + \phi^2 y^{n1}$ 
```

(2.5)

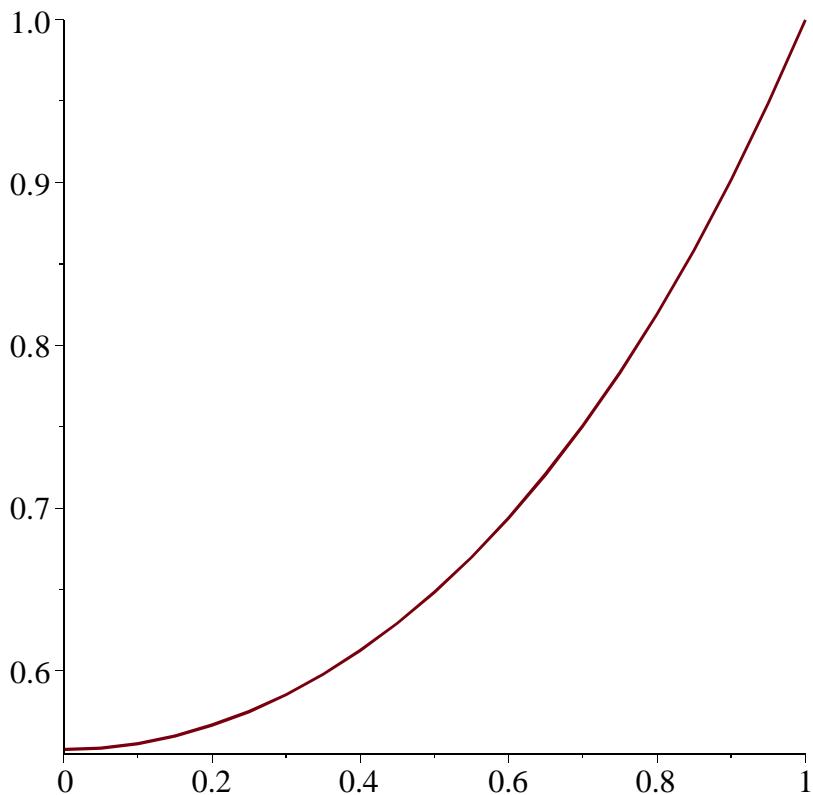
Definice parametrů metody

$$y0_1 := 1.0 \\ y0_{21} := 1.0 \quad (2.6)$$

```
> yres:= DESite2(n,f,a, b,alfa1,alfa2,beta1,beta2,gama1,gama2, eps, y0, 10):
```

"iterace = ", 0
 "y = ", [0.7999999999, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 1.]
 "iterace = ", 1, " s = ", 0.2073367222
 "y = ", [0.5516859493, 0.5526069609, 0.5553699957, 0.5599934740, 0.5665051642, 0.5749442197, 0.5853614586, 0.5978197276, 0.6123943520, 0.6291736763, 0.6482596988, 0.6697688053, 0.6938326082, 0.7205988963, 0.7502327044, 0.7829175100, 0.8188565666, 0.8582743842, 0.9014183691, 0.9485606348, 1.]
 "iterace = ", 2, " s = ", 1.709763815 10⁻⁹
 "y = ", [0.5516859509, 0.5526069627, 0.5553699977, 0.5599934757, 0.5665051658, 0.5749442208, 0.5853614590, 0.5978197272, 0.6123943508, 0.6291736745, 0.6482596969, 0.6697688037, 0.6938326071, 0.7205988953, 0.7502327038, 0.7829175099, 0.8188565669, 0.8582743848, 0.9014183694, 0.9485606348, 1.]

```
> plot(yres);
```



```
> linalg[matrix](yres);
```

0.	0.5516859509	
0.05000000000	0.5526069627	
0.10000000000	0.5553699977	
0.15000000000	0.5599934757	
0.20000000000	0.5665051658	
0.25000000000	0.5749442208	
0.30000000000	0.5853614590	
0.35000000000	0.5978197272	
0.40000000000	0.6123943508	
0.45000000000	0.6291736745	
0.50000000000	0.6482596969	(2.8)
0.55000000000	0.6697688037	
0.60000000000	0.6938326071	
0.65000000000	0.7205988953	
0.70000000000	0.7502327038	
0.75000000000	0.7829175099	
0.80000000000	0.8188565669	
0.85000000000	0.8582743848	
0.90000000000	0.9014183694	
0.95000000000	0.9485606348	
1.000000000	1.	

Definice parametr diferenciální rovnice

```
> n1:=1:  
aa:=2:  
phi:=4:
```

Definice pravé strany diferenciální rovnice

```
> f:=(x,y,dy)->-aa/x*dy + phi^2*y^n1 ;
f:=(x,y,dy) → -  $\frac{aa \, dy}{x} + \phi^2 y^{n1}$ 
```

(2,9)

Definice parametrů metody

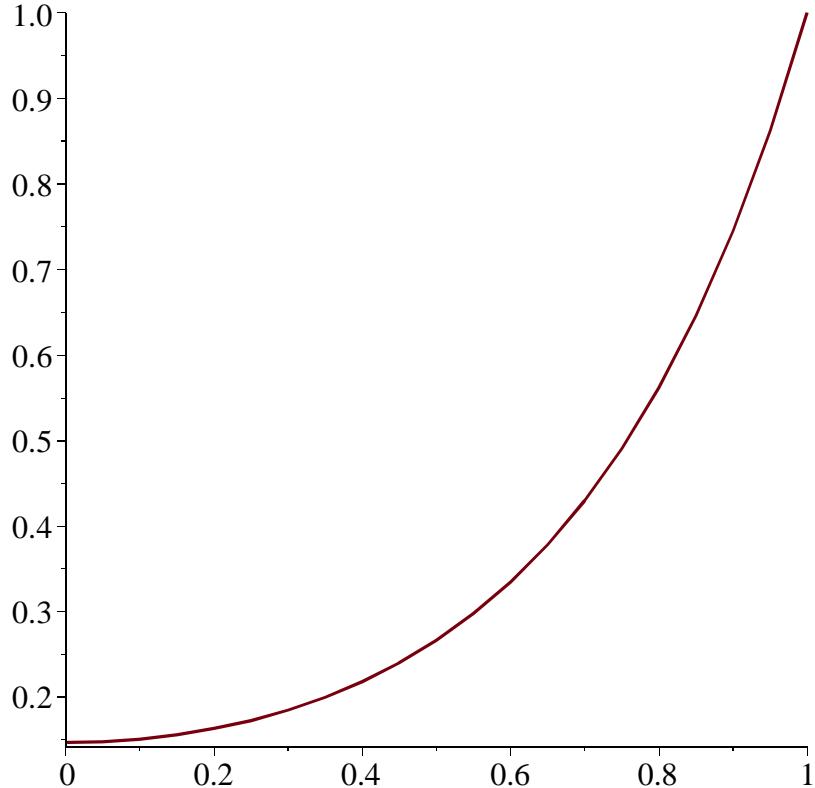
$y0_1 := 1.0$
 $y0_{21} := 1.0$ (2.10)

```

> yres := DESite2(n, f, a, b, alfa1, alfa2, beta1, beta2, gama1,
  gama2, eps, y0, 10):
          "iterace = ", 0
"y = ", [0.7999999999, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 1.]
          "iterace = ", 1, "    s = ", 0.6094049063
"y = ", [0.1472983089, 0.1482868882, 0.1512526260, 0.1562746084, 0.1634738378,
  0.1730245383, 0.1851591565, 0.2001750552, 0.2184431062, 0.2404184564,
  0.2666538008, 0.2978155843, 0.3347036422, 0.3782749025, 0.4296719079,
  0.4902570638, 0.5616537150, 0.6457953708, 0.7449846678, 0.8619639840, 1.]
          "iterace = ", 2, "    s = ", 8.689880451 10-10
"y = ", [0.1472983089, 0.1482868882, 0.1512526260, 0.1562746086, 0.1634738382, (2.11)
  0.1730245387, 0.1851591571, 0.2001750555, 0.2184431063, 0.2404184563,
  0.2666538007, 0.2978155843, 0.3347036421, 0.3782749024, 0.4296719076,
  0.4902570633, 0.5616537144, 0.6457953699, 0.7449846670, 0.8619639836, 1.]

```

> plot(yres);



> linalg[matrix](yres);

	0.	0.1472983089	
	0.050000000000	0.1482868882	
	0.100000000000	0.1512526260	
	0.150000000000	0.1562746086	
	0.200000000000	0.1634738382	
	0.250000000000	0.1730245387	
	0.300000000000	0.1851591571	
	0.350000000000	0.2001750555	
	0.400000000000	0.2184431063	
	0.450000000000	0.2404184563	
	0.500000000000	0.2666538007	(2.12)
	0.550000000000	0.2978155843	
	0.600000000000	0.3347036421	
	0.650000000000	0.3782749024	
	0.700000000000	0.4296719076	
	0.750000000000	0.4902570633	
	0.800000000000	0.5616537144	
	0.850000000000	0.6457953699	
	0.900000000000	0.7449846670	
	0.950000000000	0.8619639836	
	1.000000000000	1.	

▼ c)

Definice parametr diferenciální rovnice

```
> n1:=1:
aa:=0:
phi:=1:
```

Definice pravé strany diferenciální rovnice

```
> f:=(x,y,dy)->-aa/x*dy + phi^2*y^n1 ;
f:=(x,y,dy)→ -  $\frac{aa \, dy}{x} + \phi^2 y^{n1}$  (3.1)
```

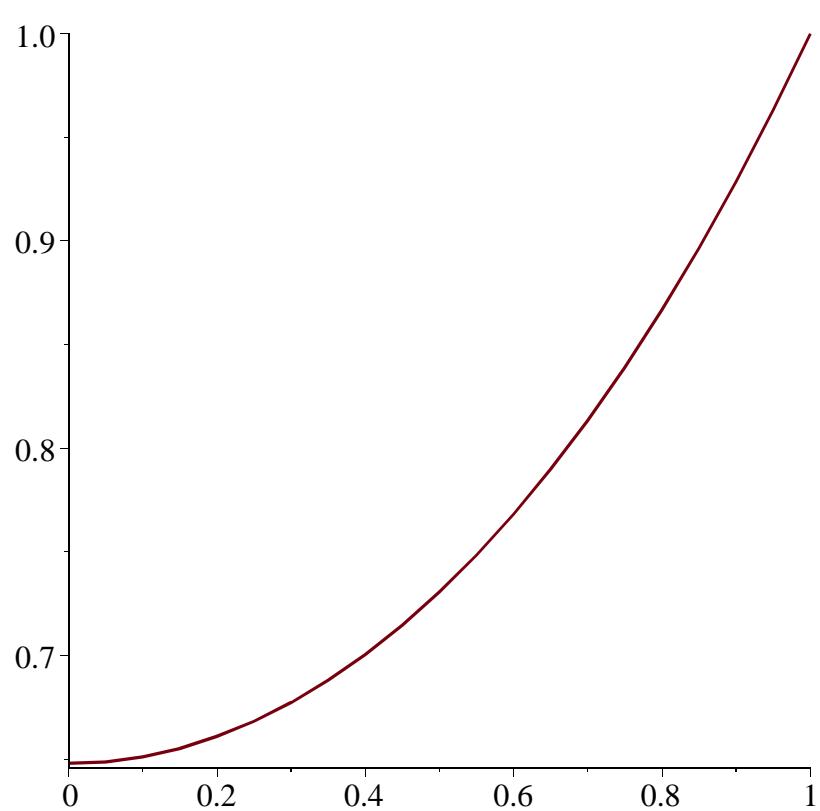
Definice parametr metody

```
> a := 0:
b := 1:
alfa1 := 0:
alfa2 := 1:
beta1 := 1:
beta2 := 0:
gama1 := 0:
gama2 := 1:
eps := 0.1e-5:
n := 20:
y0:=evalf([seq(0.8,i=1..n+1)]);
y0[1]:=1.0;
```

```

y0[n+1]:=1.0;
y0:=[0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8]
y01:=1.0
y021:=1.0
> yres:= DESite2(n,f,a, b, alfa1, alfa2, beta1, beta2, gama1, gama2,
eps, y0, 10):
"iterace = ", 0
"y = ", [0.7999999999, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8]
"iterace = ", 1, " s = ", 0.1311571478
"y = ", [0.6480902313, 0.6489013583, 0.6513347385, 0.6553964556, 0.6610966639,
0.6684496137, 0.6774736876, 0.6881914457, 0.7006296825, 0.7148194934,
0.7307963531, 0.7486002037, 0.7682755547, 0.7898715947, 0.8134423136,
0.8390466384, 0.8667485797, 0.8966173925, 0.9287277488, 0.9631599245, 1.]
"iterace = ", 2, " s = ", 9.016820882 10-9
"y = ", [0.6480902359, 0.6489013630, 0.6513347441, 0.6553964621, 0.6610966710,
0.6684496218, 0.6774736963, 0.6881914548, 0.7006296915, 0.7148195025,
0.7307963624, 0.7486002131, 0.7682755638, 0.7898716031, 0.8134423210,
0.8390466445, 0.8667485847, 0.8966173961, 0.9287277509, 0.9631599256, 1.]
> # Graf funkce y(x)
> plot(yres);

```



```
> # Tabulka hodnot funkce y(x)
> linalg[matrix](yres);
```

(3.4)

0.	0.6480902359
0.05000000000	0.6489013630
0.10000000000	0.6513347441
0.15000000000	0.6553964621
0.20000000000	0.6610966710
0.25000000000	0.6684496218
0.30000000000	0.6774736963
0.35000000000	0.6881914548
0.40000000000	0.7006296915
0.45000000000	0.7148195025
0.50000000000	0.7307963624
0.55000000000	0.7486002131
0.60000000000	0.7682755638
0.65000000000	0.7898716031
0.70000000000	0.8134423210
0.75000000000	0.8390466445
0.80000000000	0.8667485847
0.85000000000	0.8966173961
0.90000000000	0.9287277509
0.95000000000	0.9631599256
1.000000000	1.

Definice parametr diferenciální rovnice

```
> n1:=1:  
aa:=0:  
phi:=2:
```

Definice pravé strany diferenciální rovnice

```
> f:=(x,y,dy)->-aa/x*dy + phi^2*y^n1 ;
f:=(x,y,dy)→- $\frac{aa\,dy}{x}+\phi^2 y^{n1}$ 
```

(3.5)

Definice parametrů metody

$y_{0_1} := 1.0$
 $y_{0_{21}} := 1.0$ (3.6)

```

> yres:= DESite2(n,f,a, b,alfa1,alfa2,beta1,beta2,gama1,gama2,
    eps, y0, 10):
          "iterace = ", 0
    
```

$y =$, [0.7999999999, 0.8, 1.]

"iterace = ", 1, " s = ", 0.4682546864

```

"y = ", [0.2659512700, 0.2672877084, 0.2712970239, 0.2780193095, 0.2875217880,
0.2998994844, 0.3152761756, 0.3338056286, 0.3556731379, 0.3810973787,
0.4103325935, 0.4436711343, 0.4814463866, 0.5240361028, 0.5718661800,
0.6254149189, 0.6852178070, 0.7518728730, 0.8260466678, 0.9084809293, 1.]
    
```

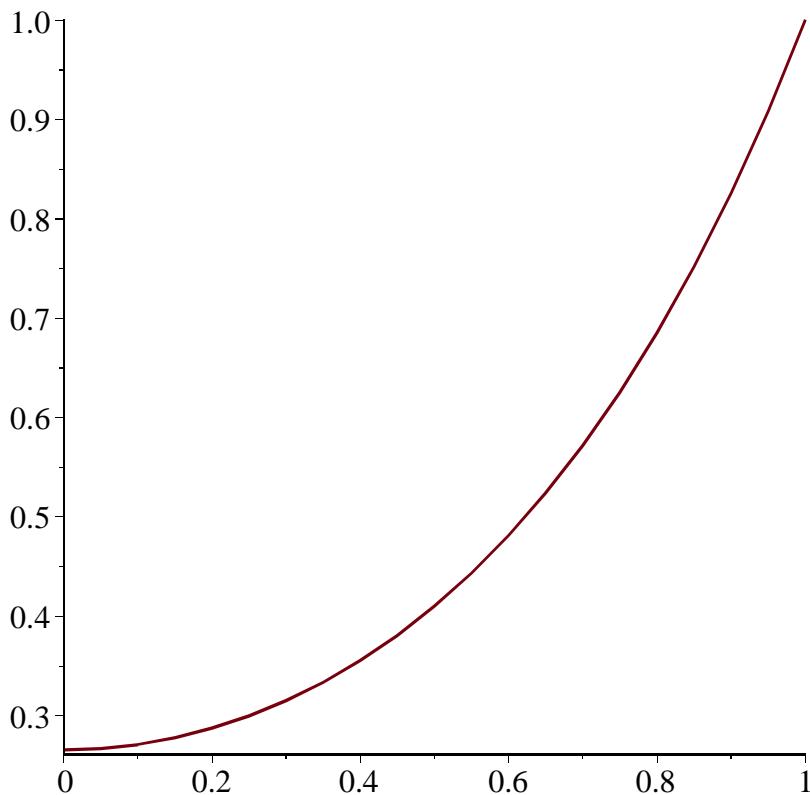
"iterace = ", 2, " s = ", 3.066550401 10^{-9}

```

"y = ", [0.2659512680, 0.2672877065, 0.2712970219, 0.2780193076, 0.2875217863, (3.7)
0.2998994830, 0.3152761744, 0.3338056276, 0.3556731370, 0.3810973779,
0.4103325925, 0.4436711330, 0.4814463849, 0.5240361006, 0.5718661777,
0.6254149166, 0.6852178048, 0.7518728711, 0.8260466662, 0.9084809282, 1.]
    
```

```

> # Graf funkce y(x)
> plot(yres);
    
```



```

> # Tabulka hodnot funkce y(x)
    
```

```
> linalg[matrix](yres);

```

	0.	0.2659512680
	0.050000000000	0.2672877065
	0.100000000000	0.2712970219
	0.150000000000	0.2780193076
	0.200000000000	0.2875217863
	0.250000000000	0.2998994830
	0.300000000000	0.3152761744
	0.350000000000	0.3338056276
	0.400000000000	0.3556731370
	0.450000000000	0.3810973779
	0.500000000000	0.4103325925
	0.550000000000	0.4436711330
	0.600000000000	0.4814463849
	0.650000000000	0.5240361006
	0.700000000000	0.5718661777
	0.750000000000	0.6254149166
	0.800000000000	0.6852178048
	0.850000000000	0.7518728711
	0.900000000000	0.8260466662
	0.950000000000	0.9084809282
	1.000000000000	1.

(3.8)

Definice parametr diferenciální rovnice

```
> n1:=1:  
aa:=0:  
phi:=4:
```

Definice pravé strany diferenciální rovnice

$f := (x, y, dy) \rightarrow -\frac{aa}{x} dy + \phi^2 y^n l$

Definice parametrů metody

0.8, 0.8]

$y\theta_1 := 1.0$

$y\theta_{21} := 1.0$

(3.10)

> **yres:= DESite2(n,f,a, b, alfa1, alfa2, beta1, beta2, gama1, gama2,**
eps, y0, 10):

"iterace = ", 0

"y = ", [0.7999999999, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8, 0.8,
0.8, 0.8, 0.8, 1.]

"iterace = ", 1, " s = ", 0.7414509126

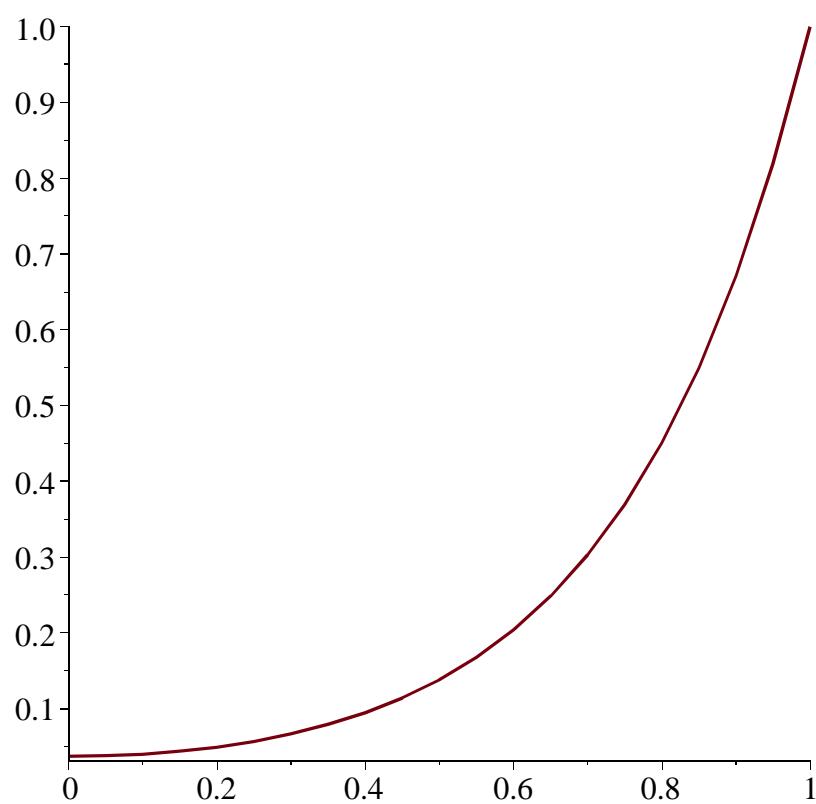
"y = ", [0.03678801740, 0.0375387932, 0.0397911206, 0.0436350928, 0.0492244686,
0.0567828231, 0.0666124907, 0.0791066582, 0.0947650922, 0.1142141296,
0.1382317326, 0.1677786047, 0.2040366210, 0.2484561022, 0.3028138274,
0.3692841055, 0.4505257480, 0.5497884204, 0.6710426295, 0.8191385439, 1.]

"iterace = ", 2, " s = ", $9.712016986 \cdot 10^{-10}$

"y = ", [0.03678801686, 0.03753879272, 0.03979112029, 0.04363509266, (3.11)
0.04922446874, 0.05678282357, 0.06661249135, 0.07910665878, 0.09476509256,
0.1142141300, 0.1382317327, 0.1677786047, 0.2040366209, 0.2484561019,
0.3028138270, 0.3692841052, 0.4505257476, 0.5497884199, 0.6710426292,
0.8191385436, 1.]

> # Graf funkce y(x)

> plot(yres);



```
> # Tabulka hodnot funkce y(x)
> linalg[matrix](yres);
```

(3.12)

$$\left[\begin{array}{cc}
0. & 0.03678801686 \\
0.05000000000 & 0.03753879272 \\
0.10000000000 & 0.03979112029 \\
0.15000000000 & 0.04363509266 \\
0.20000000000 & 0.04922446874 \\
0.25000000000 & 0.05678282357 \\
0.30000000000 & 0.06661249135 \\
0.35000000000 & 0.07910665878 \\
0.40000000000 & 0.09476509256 \\
0.45000000000 & 0.1142141300 \\
0.50000000000 & 0.1382317327 \\
0.55000000000 & 0.1677786047 \\
0.60000000000 & 0.2040366209 \\
0.65000000000 & 0.2484561019 \\
0.70000000000 & 0.3028138270 \\
0.75000000000 & 0.3692841052 \\
0.80000000000 & 0.4505257476 \\
0.85000000000 & 0.5497884199 \\
0.90000000000 & 0.6710426292 \\
0.95000000000 & 0.8191385436 \\
1.00000000000 & 1.
\end{array} \right] \quad (3.12)$$