

TURBULENTNÍ DIFÚZE

$$c_i = \bar{c}_i + c'_i \quad \text{sprům.} \rightarrow \bar{c}_i = \bar{\bar{c}}_i + \bar{c}'_i$$

$$\vec{v}_m = \vec{\bar{v}}_m + \vec{v}'_m$$

$$\bar{c}_i = \bar{\bar{c}}_i + \bar{c}'_i$$



$$\begin{aligned} \text{R.K.: } \frac{\partial(\bar{c}_a + \bar{c}'_a)}{\partial t} + \nabla \cdot [(\bar{c}_a + \bar{c}'_a)(\vec{\bar{v}}_m + \vec{v}'_m)] - D_{ab} \nabla^2 (\bar{c}_a + \bar{c}'_a) &= -k(\bar{c}_a + \bar{c}'_a) \\ &= -k(\bar{\bar{c}}_a + \bar{c}'_a)^2 \\ \nabla \cdot [\bar{c}_a \vec{\bar{v}}_m + \underbrace{\bar{c}_a \vec{v}'_m + \bar{c}'_a \vec{\bar{v}}_m}_{\vec{J}_{Ta}} + \bar{c}'_a \vec{v}'_m] &= -k(\bar{\bar{c}}_a^2 + 2\bar{\bar{c}}_a \bar{c}'_a + \bar{c}'_a^2) \end{aligned}$$

$$\begin{aligned} \frac{\partial \bar{c}_a}{\partial t} + \nabla \cdot (\bar{c}_a \vec{\bar{v}}_m + \bar{c}'_a \vec{v}'_m) - D_{ab} \nabla^2 \bar{c}_a &= -k \bar{c}_a \\ + \nabla \cdot \vec{J}_a^m + \nabla \cdot \vec{J}_{Ta} + \nabla \cdot \vec{J}_{Da} &= -k(\bar{\bar{c}}_a^2 + \bar{c}'_a^2) \\ &= \sigma_a + \sigma_{Ta} \end{aligned}$$

$$\vec{J}_{Ta} = -D_{Ta} \nabla \bar{c}_a$$

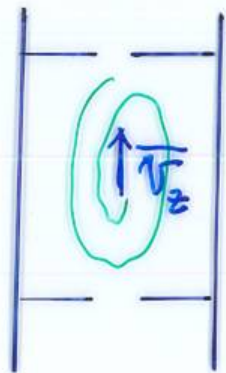
$$\vec{J}_a^m = -(D_T + D_{ab}) \nabla \bar{c}_a$$

$$\frac{D_T}{D_{ab}} \quad 10^2 (g), \quad 10^5 (l)$$

DISPERSNÍ TOK :

SUPERPOSICE : PÍST. TOK + NEUSPOŘ. TOK
(V MAKROMĚŘÍTKU)

VYROVNÁVÁNÍ KONC. PROMÍCH. VE VELKÝCH MĚŘ.,
SROVNATELNÝCH S ROZMĚRY ZAŘÍZ.



$$\frac{\partial c_i}{\partial \tau} + \bar{v}_z \frac{\partial c_i}{\partial z} - D_z \frac{\partial^2 c_i}{\partial z^2} = \sigma_i$$

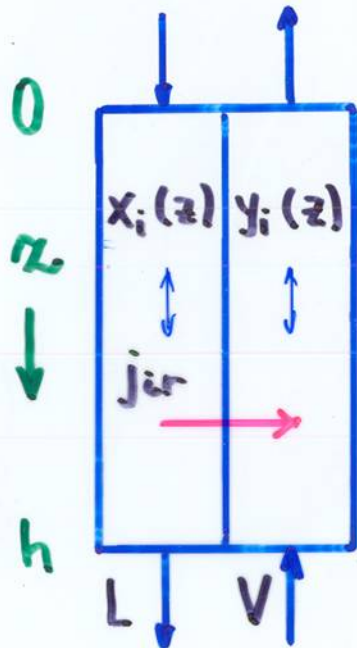
$$\bar{v}_z = \frac{\dot{V}}{S_E}$$

KOEF. AX. DISPERSE (PODÉL.)

RAD. DISP. (PŘÍČ.)

$$\frac{\partial c_i}{\partial \tau} + \bar{v}_z \frac{\partial c_i}{\partial z} - D_z \frac{\partial^2 c_i}{\partial z^2} - \frac{D_r}{r} \frac{\partial}{\partial r} \left(r \frac{\partial c_i}{\partial r} \right) = \sigma_i$$

USTÁL. $\Rightarrow$ + AX. DISPERZE



$j_L = \frac{\dot{n}_L}{\varepsilon \varphi_L S}$
 $\frac{d(j_L x_i)}{dz} - c_L D_L \frac{d^2 x_i}{dz^2} = \sigma_{iL} \quad (L \rightarrow V)$
 $\sigma_i = -j_r a = \sigma_{iL} \varepsilon \varphi_L = -\sigma_{iV} \varepsilon \varphi_V$
 $\frac{d(j_V y_i)}{dz} - c_V D_V \frac{d^2 y_i}{dz^2} = \sigma_{iV}$
 $-j_V = \frac{\dot{n}_V}{\varepsilon \varphi_V S}$
 $(\varphi_L + \varphi_V = 1) \quad j_r a = k_x a (x_i - x_i^*) = k_y a (y_i^* - y_i) = K_x a (x_i - x_i^*) = K_y a (y_i^* - y_i)$

$$\Rightarrow \frac{dx_i}{dz} - \frac{\varepsilon \varphi_L S c_L h}{\dot{n}_L h} \frac{d^2 x_i}{dz^2} = - \frac{K_x a S h}{\dot{n}_L} (x_i - x_i^*)$$

$z = \frac{z}{h} \quad \frac{1}{Pe_L} = \frac{D_L}{v_L h} \quad \bar{N}_x = \frac{h}{H_x}$

$$- \frac{dy_i}{dz} - \frac{1}{Pe_V} \frac{d^2 y_i}{dz^2} = \bar{N}_y (y_i^* - y_i)$$

PÍST. TOK

$Pe \rightarrow \infty$
 $D = 0$

* MÍ'S. $Pe = 0$
 $D \rightarrow \infty$

D.P. (DANCKWERTS)

$$z = \bar{z} = 0 \quad \begin{array}{c} \downarrow \dot{n}_{L0}, x_{i0-}, D_L = 0 \\ \downarrow \dot{n}_{L0}, x_{i0+}, D_L > 0 \end{array}$$

$$\begin{array}{c} z = h \\ \bar{z} = 1 \end{array} \quad \begin{array}{c} \downarrow \dot{n}_{L1}, x_{i1-}, D_L > 0 \\ \downarrow \dot{n}_{L1}, x_{i1+}, D_L = 0 \end{array}$$

$$\downarrow (z = \frac{z}{h})$$

$$z = \bar{z} = 0 \quad \begin{array}{c} \uparrow \dot{n}_{v0}, y_{i0}, D_v = 0 \\ \uparrow \dot{n}_{v0}, y_{i0}, D_v > 0 \end{array}$$

$$\begin{array}{c} z = h \\ \bar{z} = 1 \end{array} \quad \begin{array}{c} \uparrow \dot{n}_{v1}, y_{i1-}, D_v > 0 \\ \uparrow \dot{n}_{v1}, y_{i1+}, D_v = 0 \end{array}$$

$$\dot{n}_{L0} x_{i0-} = \dot{n}_{L0} x_{i0+} - c_L D_L S_L \left. \frac{dx_i}{dz} \right|_{0+}$$

$$\underline{\underline{\frac{dx_i}{dz} - Pe_L (x_i - x_{i0-}) = 0}}$$

$$x_{i1-} = x_{i1+}$$

$$\dot{n}_{L1} x_{i1-} - c_L D_L S_L \left. \frac{dx_i}{dz} \right|_{h-} = \dot{n}_{L1} x_{i1}$$

$$\frac{1}{Pe_L} \frac{dx_i}{dz} = 0 \Rightarrow \underline{\underline{\frac{dx_i}{dz} = 0}}$$

$$\underline{\underline{\frac{dy_i}{dz} = 0}}$$

$$\underline{\underline{\frac{dy_i}{dz} + Pe_v (y_i - y_{i1+}) = 0}}$$

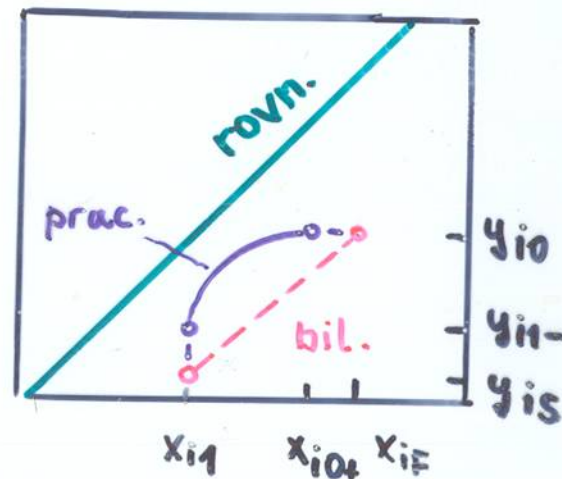
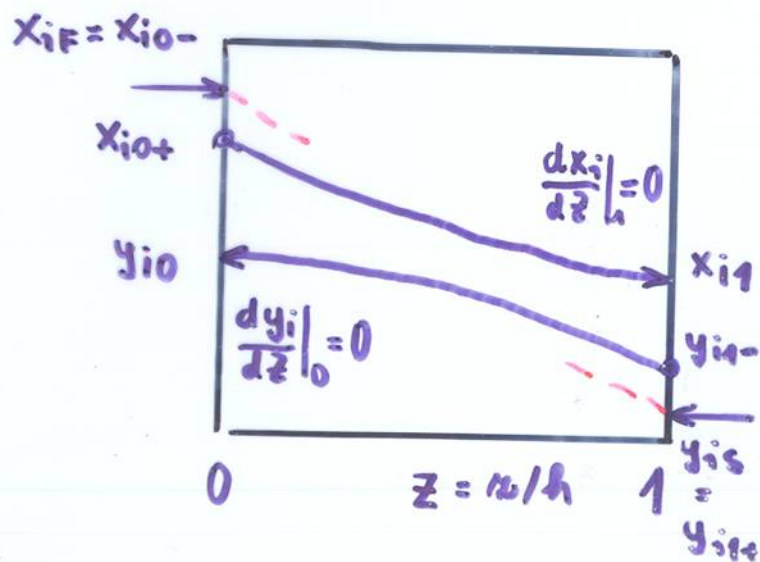
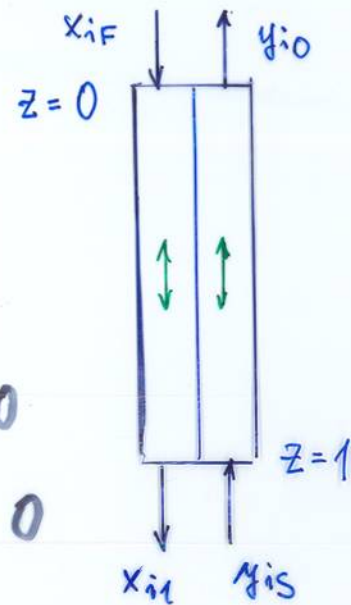
$\Rightarrow$ s ax. dispersí (EXTR.)

$$\frac{dx_i}{dz} + \frac{1}{Pe_L} \frac{d^2 x_i}{dz^2} = -N_x (x_i - x_i^*)$$

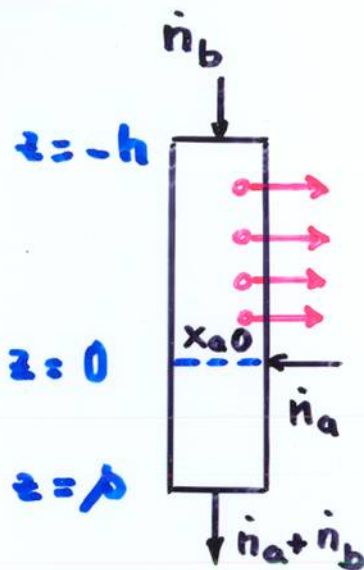
$$-\frac{dy_i}{dz} - \frac{1}{Pe_v} \frac{d^2 y_i}{dz^2} = N_y (y_i^* - y_i)$$

$$z=0 \quad \frac{dx_i}{dz} - Pe_L (x_i - x_{iF}) = 0, \quad \frac{dy_i}{dz} = 0$$

$$z=1 \quad \frac{dx_i}{dz} = 0, \quad \frac{dy_i}{dz} + Pe_v (y_i - y_{iS}) = 0$$



STAT. MĚŘ. AX. DISPERSE



$z \leq 0 :$

$$0 = x_a j - cD \frac{dx_a}{dz}$$

$j_a = 0 \quad j = j_a + j_b = j_b$

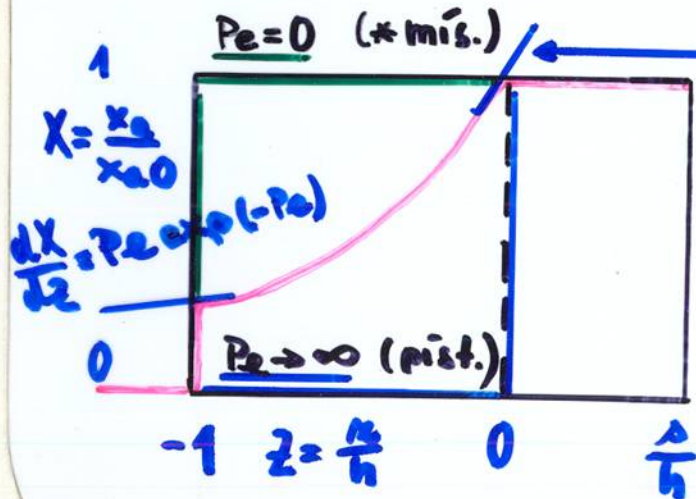
$$x_{a0} = \frac{j_{a0}}{j_a + j_b} = \frac{n_a}{n_a + n_b}$$

$$\frac{j}{cD} \int_0^z dz = \int_{x_{a0}}^{x_a} \frac{dx_a}{x_a}$$

$$\frac{x_a}{x_{a0}} = \exp\left(\frac{jz}{cD} \cdot \frac{h}{h}\right) = \exp\left(\frac{jh}{cD} \cdot \frac{z}{h}\right)$$

$$X = \exp(Pe \cdot z)$$

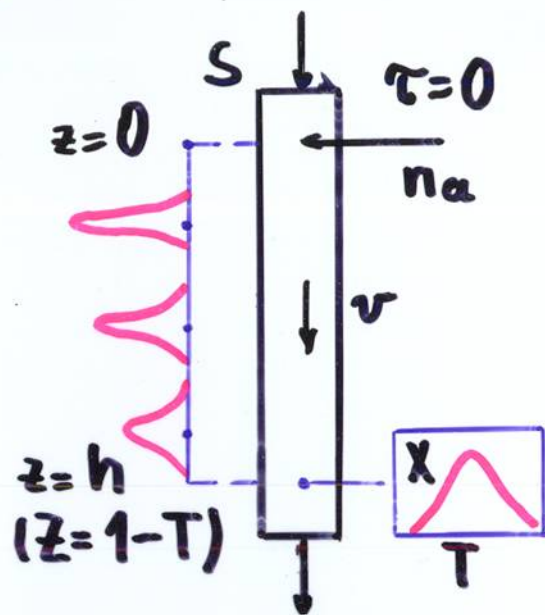
$$\frac{jh}{cD} = \frac{Vh}{SD} = \frac{vh}{D}$$



$$\frac{dX}{dz} = Pe \exp(Pe \cdot 0) = Pe$$

$$\frac{dX}{dz} = Pe \exp(Pe \cdot z)$$

$X(-\infty) = 0$



DYNAM. MĚŘ. AX. DISPERSE

$$\frac{\partial c_a}{\partial \tau} + v \frac{\partial c_a}{\partial z} - D \frac{\partial^2 c_a}{\partial z^2} = \frac{m_a}{S} \delta(\tau) \delta(z)$$

$$\delta(y) = 0 \quad y \neq 0, \quad \int_{-\infty}^{\infty} \delta(y) dy = 1$$

$$z = \frac{z - v\tau}{h} = \frac{z}{h} - T$$

$$X = \frac{c_a S h}{n_a}, \quad Pe = \frac{v h}{D}$$

$$\frac{\partial X}{\partial T} + \frac{1}{Pe} \frac{\partial^2 X}{\partial z^2} = \delta(T) \delta(z)$$

$$z=0, \quad \frac{\partial X}{\partial z} = 0 \quad (\text{symetrie})$$

$$z \rightarrow \infty, \quad X = 0$$

$$X = \sqrt{\frac{Pe}{4\pi T}} \exp \left[-\frac{Pe z^2}{4T} \right]$$

$$z=h, \quad z=1-T:$$

$$X = \sqrt{\frac{Pe}{4\pi T}} \exp \left[-\frac{Pe(1-T)^2}{4T} \right]$$

$$\frac{\partial c_a}{\partial \tau} = \frac{\partial c_a}{\partial T} \frac{\partial T}{\partial \tau} + \frac{\partial c_a}{\partial z} \frac{\partial z}{\partial \tau} = \frac{\partial c_a}{\partial T} \frac{v}{h} - \frac{\partial c_a}{\partial z} \frac{v}{h}$$

$$\frac{\partial c_a}{\partial z} = \frac{\partial c_a}{\partial z} \frac{\partial z}{\partial z} = \frac{\partial c_a}{\partial z} \frac{1}{h} \quad \frac{\partial^2 c_a}{\partial z^2} = \frac{\partial^2 c_a}{\partial z^2} \frac{1}{h^2}$$

$$\frac{m_a}{S} \delta(\tau) \delta(z) = \frac{m_a}{S} \frac{h}{v} \frac{v}{h^2} \delta(T) \delta(z)$$

MOMENTY

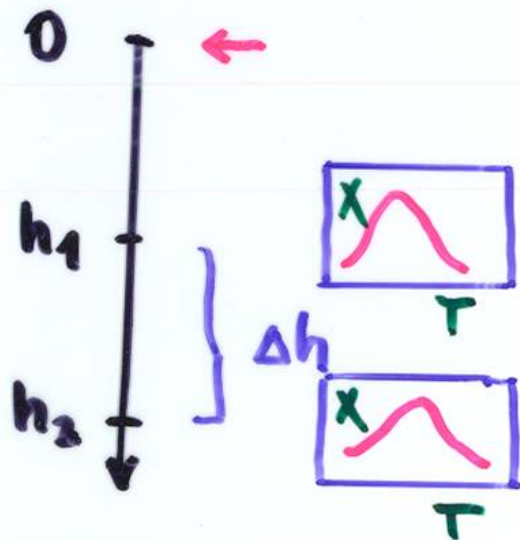
$$\mu = \frac{\int_0^{\infty} X(\tau) \tau d\tau}{\int_0^{\infty} X(\tau) d\tau}, \quad \sigma^2 = \frac{\int_0^{\infty} (\tau - \mu)^2 X(\tau) d\tau}{\int_0^{\infty} X(\tau) d\tau} = \frac{\int_0^{\infty} X(\tau) \tau^2 d\tau}{\int_0^{\infty} X(\tau) d\tau} - \mu^2$$

$$\mu = \frac{2}{Pe} + 1$$

$$\mu_{\sigma} = \mu \frac{h}{v}$$

$$\sigma^2 = \frac{8}{Pe^2} + \frac{2}{Pe}$$

$$\sigma_{\sigma}^2 = \sigma^2 \frac{h^2}{v^2}$$



$$T^x = \frac{\bar{v}}{\Delta h}, \quad Pe^x = \frac{v \Delta h}{D}$$

$$\sigma_2^2 - \sigma_1^2 = \frac{2}{Pe^x}$$

PŘEVODOVÉ JEDNOTKY

$$\dot{n}_L \frac{dx_i}{dz} = -k_x a S (x_i - x_i^r)$$

$$n_x = - \int_{x_{i0}}^{x_{i1}} \frac{dx_i}{x_i - x_i^r} = \frac{k_x a S}{\dot{n}_L} \int_0^h dz = \frac{k_x a S}{\dot{n}_L} h = \frac{h}{h_x}$$

vnější

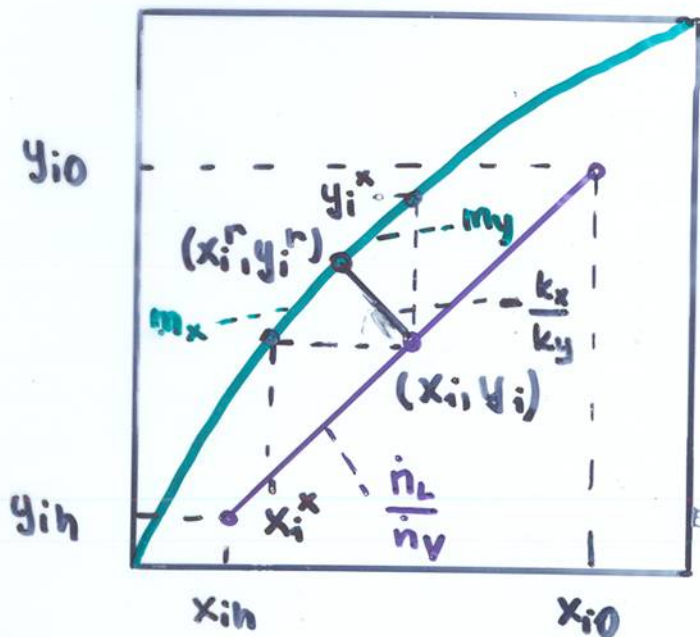
vnitřní

$$\frac{1}{K_x} = \frac{1}{k_x} + \frac{1}{n_x k_y} \cdot \frac{\dot{n}_v}{\dot{n}_L} / \frac{\dot{n}_L}{a S h}$$

$$H_x = h_x + \underbrace{\left(\frac{\dot{n}_L}{\dot{n}_v n_x} \right)}_{A_{mx}} h_y$$

$$\frac{1}{K_y} = \frac{m_y}{k_x} + \frac{1}{k_y}$$

$$H_y = \underbrace{\left(\frac{m_y \dot{n}_v}{\dot{n}_L} \right)}_{S_{my}} h_x + h_y$$



n_x	n_y	N_x	N_y
x_i	y_i	x_i	y_i
$x_i - x_i^r$	$y_i^r - y_i$	$x_i - x_i^x$	$y_i^x - y_i$
k_x	k_y	K_x	K_y
$\dot{n}_L$	$\dot{n}_v$	$\dot{n}_L$	$\dot{n}_v$
h_x	h_y	H_x	H_y

PJ: PŘECHÁZÍ 1 SLOŽKA

není konst.

$$\frac{d(\dot{n}_L x_a)}{dz} = \dot{n}_L (1-x_a) \frac{d\left(\frac{x_a}{1-x_a}\right)}{dz} = \dot{n}_L^{-a} \frac{dX_a}{dz} = -k_x a S (X_a - X_a^r) \quad (1)$$

$$\frac{d}{dz} \left(\frac{x_a}{1-x_a} \right) = \frac{1}{(1-x_a)^2} \frac{dx_a}{dz}$$

$$\frac{\dot{n}_L}{1-x_a} \frac{dx_a}{dz} = -k_x a S (x_a - x_a^r) \quad (2)$$

$$k_x = \frac{k_x^0}{(1-x_a)_{es}} \quad (1-x_a)_{es} = \frac{x_a - x_a^r}{\ln \frac{1-x_a^r}{1-x_a}}$$

$\frac{\dot{n}_L}{k_x}$ konst. (spíše než k_x)

$$x_a = \frac{X_a}{1+X_a}, \quad x_a^r = \frac{X_a^r}{1+X_a^r}$$

$$(1) \quad dz = - \frac{\dot{n}_L^{-a}}{k_x a S} \cdot \frac{dX_a}{X_a - X_a^r} \quad (2a) \quad (3a)$$

$$(2) \quad dz = - \frac{\dot{n}_L}{k_x a S} \cdot \frac{dx_a}{(1-x_a)(x_a - x_a^r)}$$

$$(3) \quad dz = - \frac{\dot{n}_L}{k_x^0 a S} \cdot \frac{(1-x_a)_{es} dx_a}{(1-x_a)(x_a - x_a^r)} = - \frac{\dot{n}_L}{k_x^0 a S} \cdot \frac{dx_a}{(1-x_a) \ln \frac{1-x_a^r}{1-x_a}}$$

$$(2a) \quad dz = - \frac{\dot{n}_L}{k_x a S} \cdot \frac{(1+X_a^r) dX_a}{X_a - X_a^r} \quad \dot{n}_L = \dot{n}_L^{-a} (1+X_a)$$

$$(3a) \quad dz = \frac{\dot{n}_L}{k_x^0 a S} \cdot \frac{(1+X_a)_{es} dX_a}{(1+X_a)(X_a - X_a^r)} = - \frac{\dot{n}_L}{k_x^0 a S} \cdot \frac{dX_a}{(1+X_a) \ln \frac{1+X_a}{1+X_a^r}}$$



1.

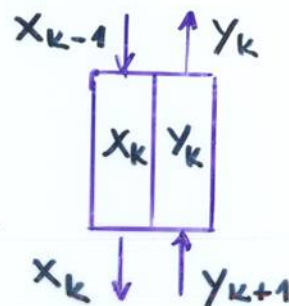
* mlich L
* mlich V

$$Pe_L = 0$$

$$Pe_V = 0$$

$$N_x = \int_{x_{k-1}}^{x_k} \frac{dx}{x - x^*}$$

$$N_y = \int_{y_{k+1}}^{y_k} \frac{dy}{y^* - y}$$



$$\dot{m}_L (x_{k-1} - x_k) = \dot{m}_V (y_k - y_{k+1}) =$$

$$= N_x \dot{m}_L (x_k - x_k^*) = N_y \dot{m}_V (y_k^* - y_k)$$

$$N_x = \frac{x_{k-1} - x_k}{x_k - x_k^*}$$

$$N_y = \frac{y_k - y_{k+1}}{y_k^* - y_k}$$

$$\frac{1}{E_x^M} = 1 + \frac{1}{N_x}$$

$$\frac{1}{E_y^M} = 1 + \frac{1}{N_y}$$

$$\frac{1}{E} = 1 \quad \text{pro} \quad N \rightarrow \infty, K \rightarrow \infty$$

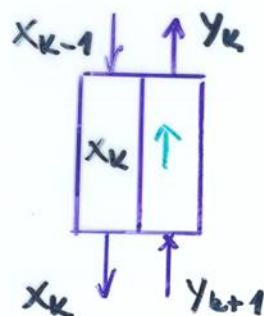
2.

* mlich L
pist. V

$$Pe_L = 0$$

$$Pe_V = \infty$$

konst



$$- \frac{dy}{dz} = N_y (y_k^* - y)$$

$$- \int_{y_k}^{y_{k+1}} \frac{dy}{y_k^* - y} = N_y \int_0^1 dz$$

$$\ln \frac{y_k^* - y_{k+1}}{y_k^* - y_k} = -N_y$$

$$\frac{y_k^* - y_{k+1}}{y_k^* - y_k} = e^{-N_y}$$

$$E_y^M = 1 - e^{-N_y}$$

$$E_x^M = \frac{x_{k-1} - x_k}{x_{k-1} - x_k^*}$$

$$E_y^M = \frac{y_k - y_{k+1}}{y_k^* - y_{k+1}}$$